

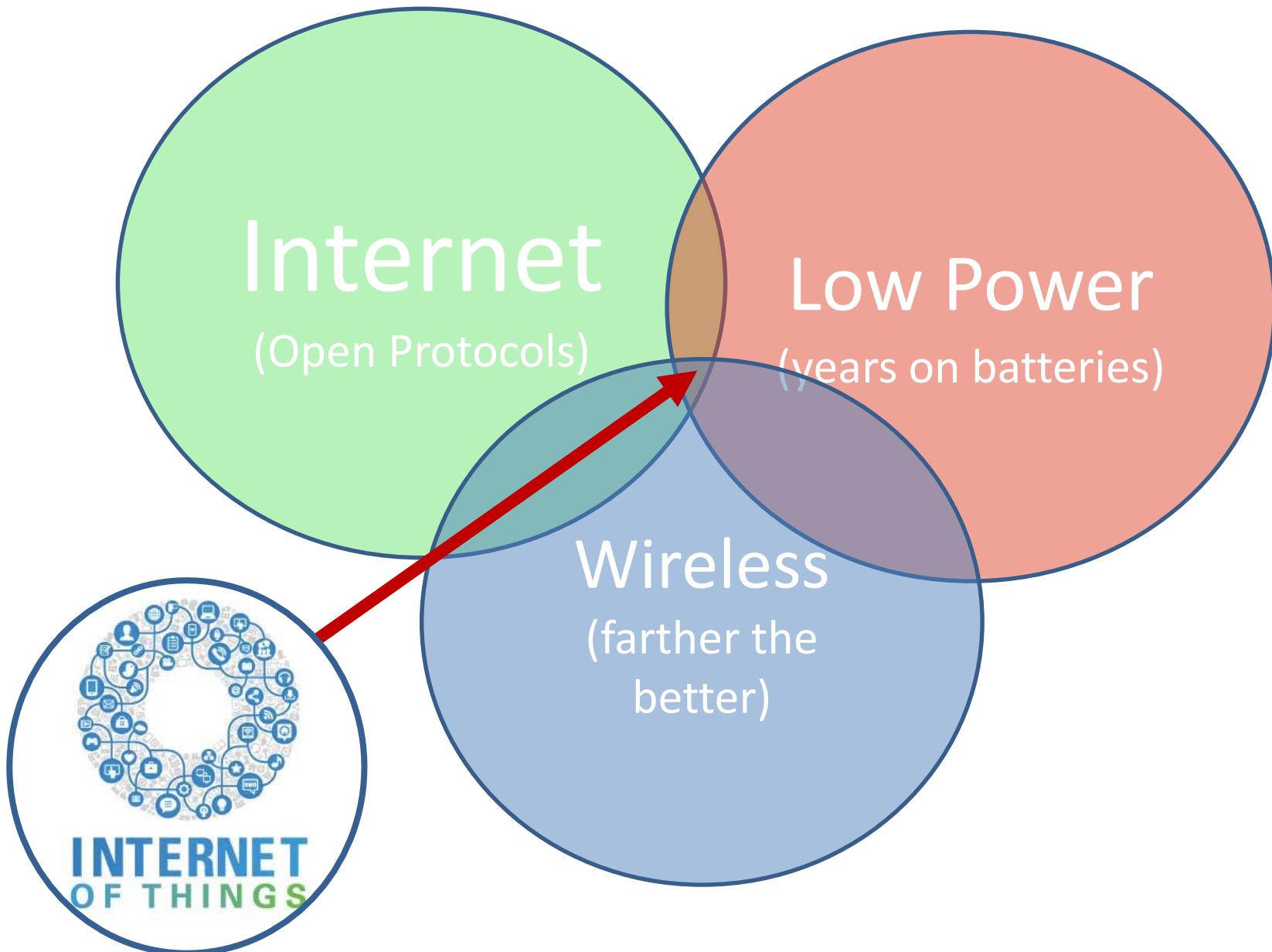


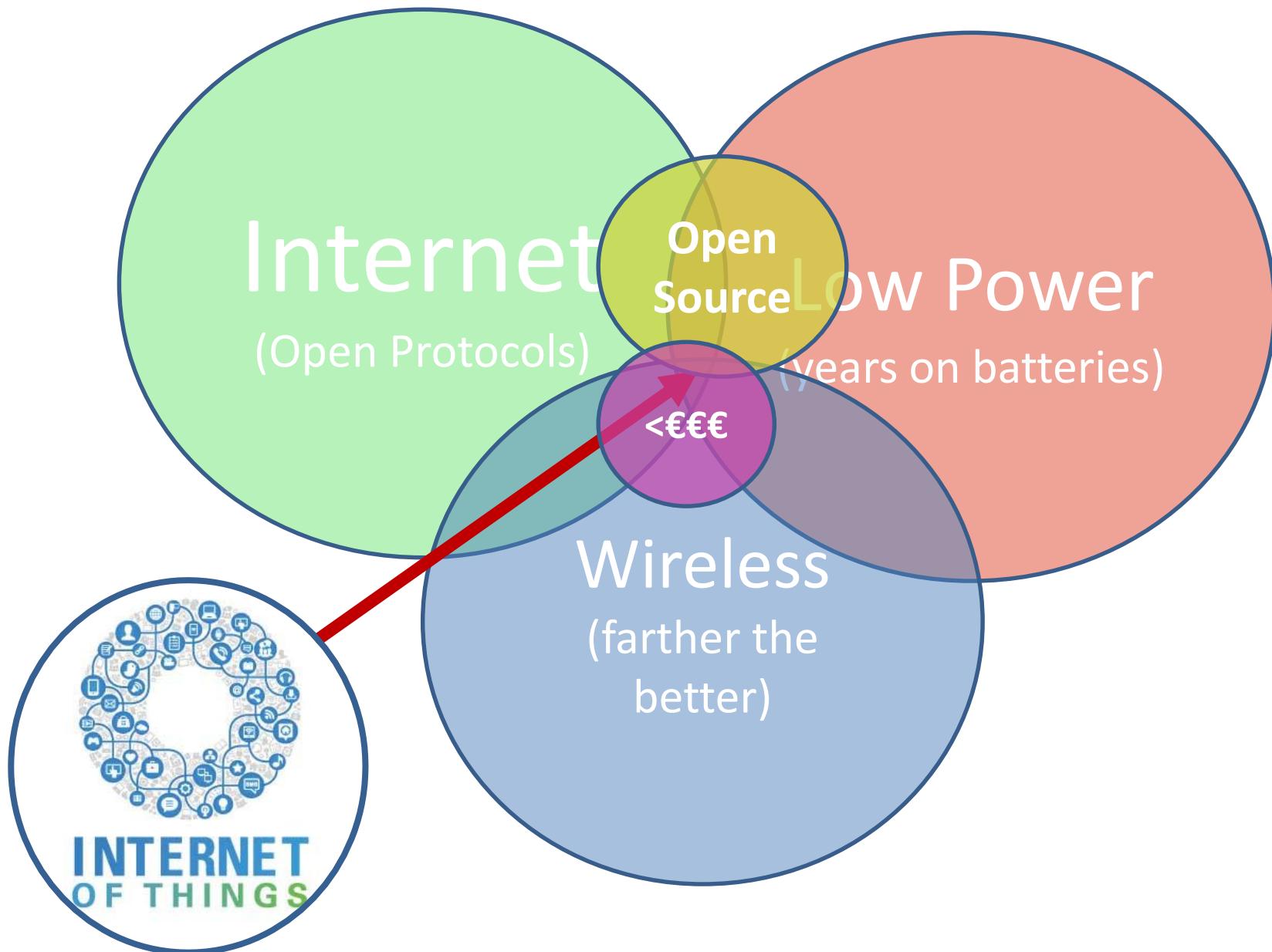
*Internet of Things*  
**IN 5 DAYS**

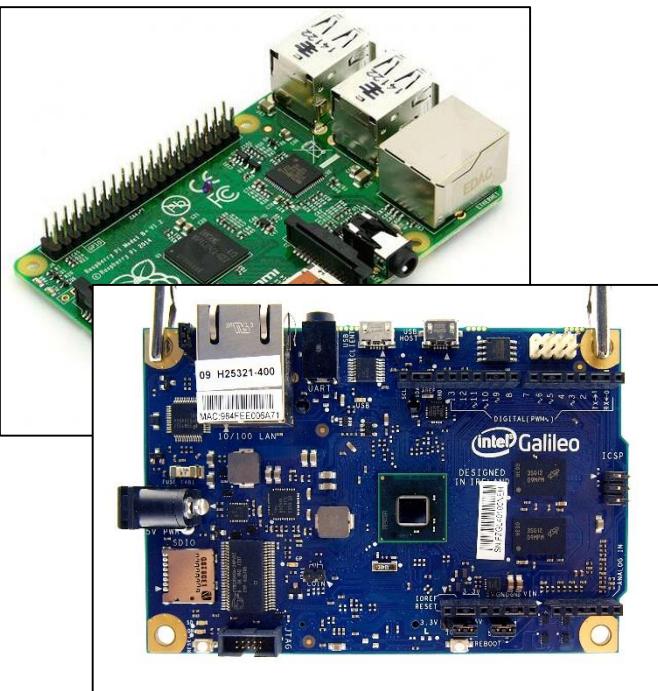
# Contiki introduction

Antonio Liñán Colina,  
Zolertia



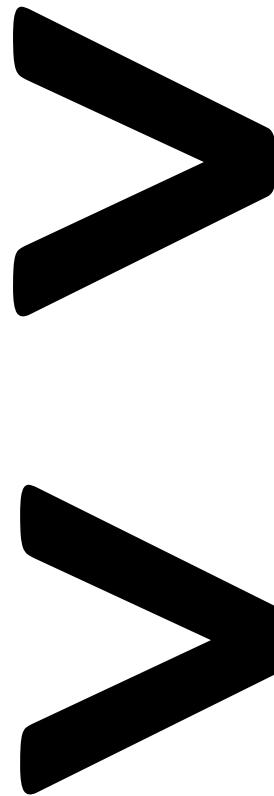




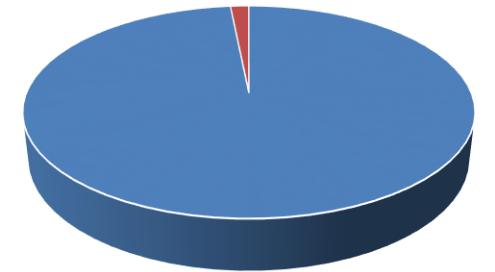


200-500 mA @ 5V → 1- 2.5 Watts  
USB power bank 7Ah → 19.6 hours

DietPi build → 16MB RAM (1GB available)  
Typical application: 50KB (0.005%)



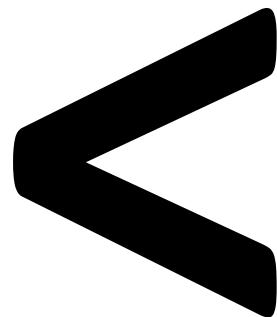
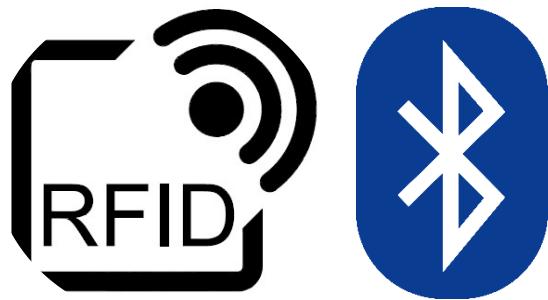
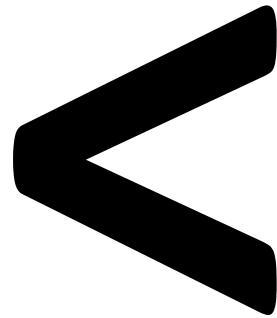
Processing power



■ Unused ■ System ■ Required ■

<http://fuzon.co.uk/phpbb/viewtopic.php?f=8&t=6>

<http://www.digikey.com/en/resources/conversion-calculators/conversion-calculator-battery-life>



30m

## Spark Core's current draw posting to Ubidots

Deep sleep mode and wake-up to post every minute (scaled to mA)



40.5 mA (avg) @ 5V → 225mW

USB power bank 7Ah → 121h (5 days)

<http://www.ubidots.com/>

<https://www.particle.io/>

<https://www.hackster.io/4354/potato-powered-iot-947b69>



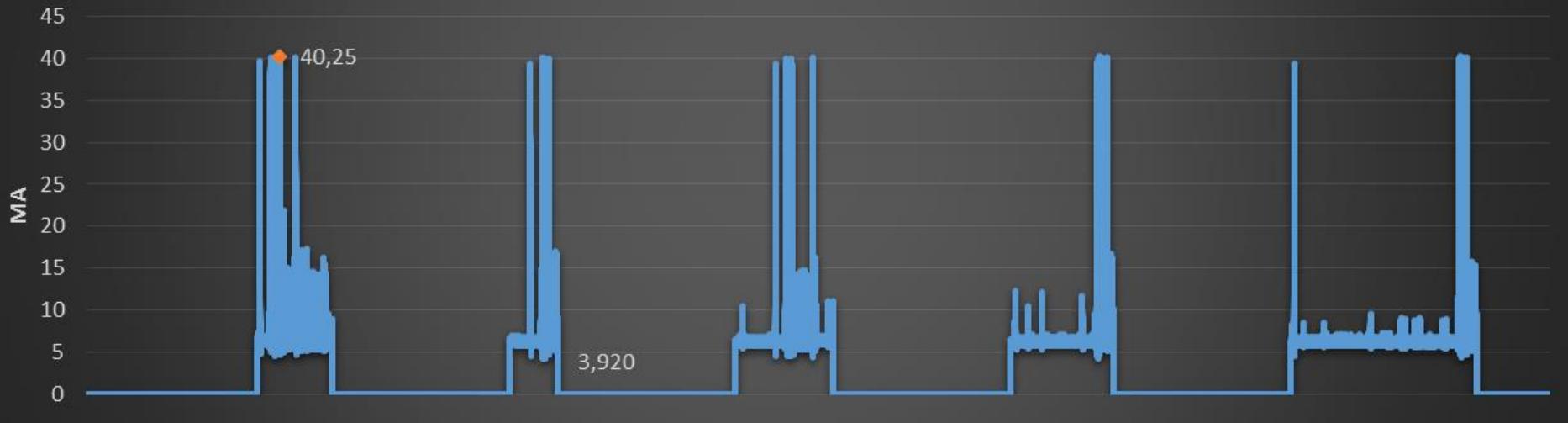
\* Commercial solutions without special antennas

<http://www.atmel.com/>

## Re-Mote's current draw posting to Ubidots

One minute post period (scaled to mA)

AVG: 2.611 mA

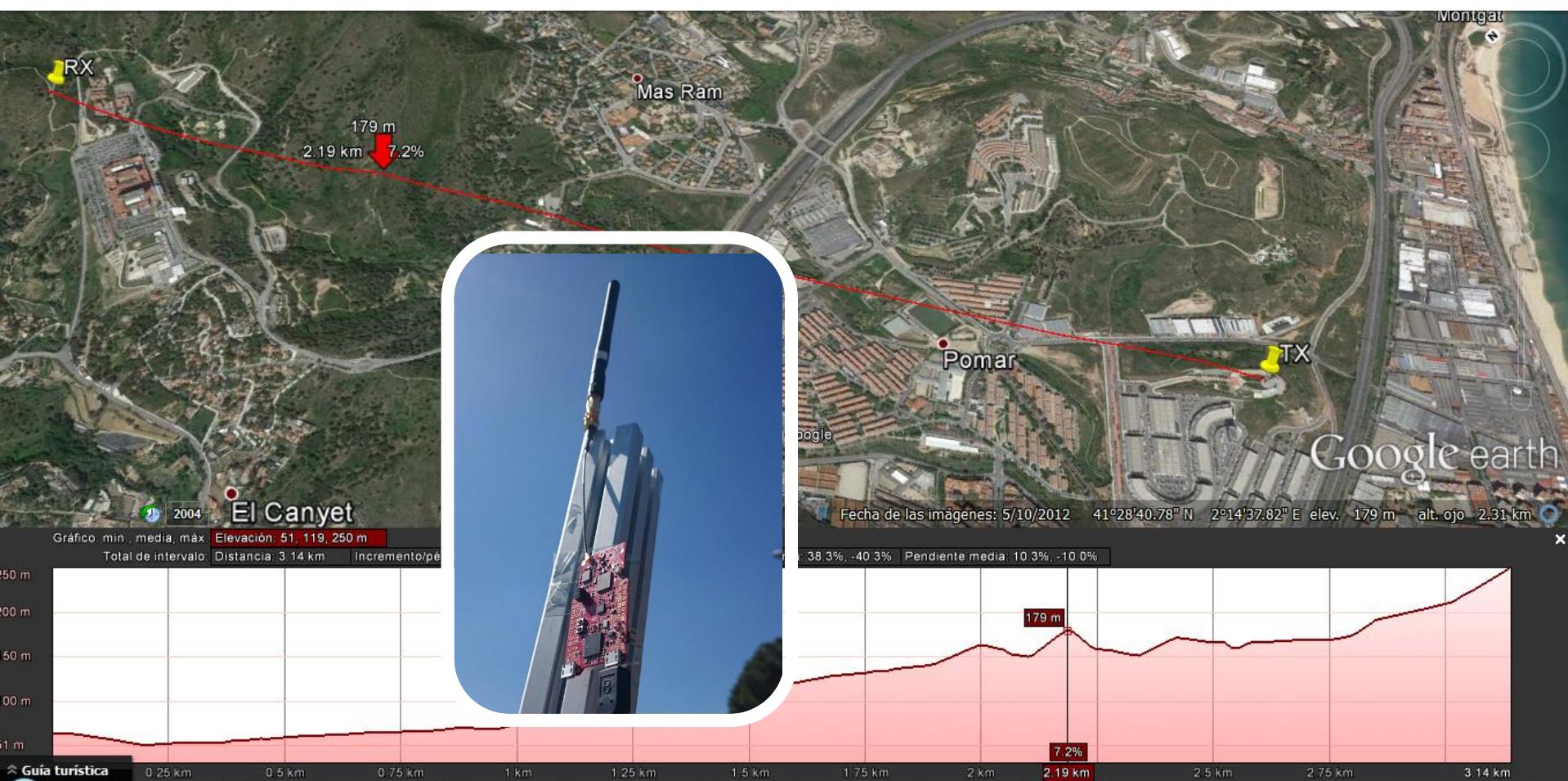


2.6 mA (avg) @ 5V → 13 mW  
USB power bank 7Ah → 1884h (78,5 days)

<http://zolertia.io/>

<http://www.ubidots.com/>

<https://www.hackster.io/4354/potato-powered-iot-947b69>

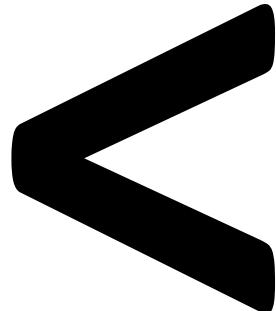
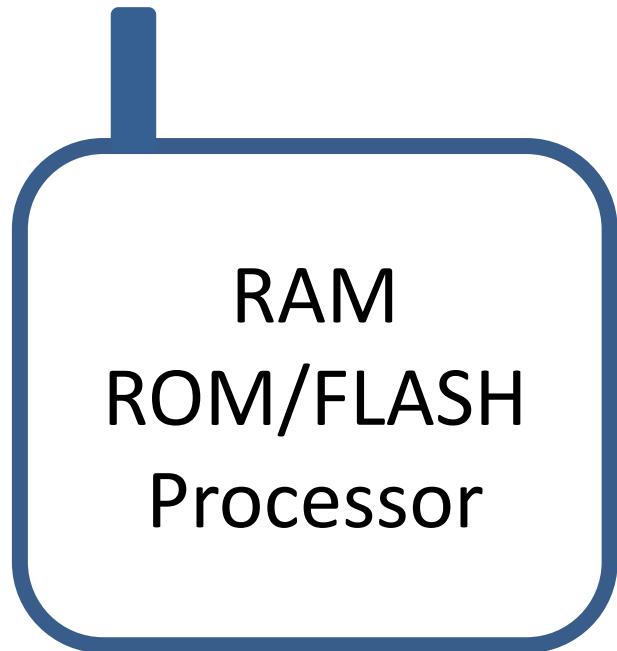


Zolertia RE-mote prototype A  
868MHz, 3.14Km @50Kbps  
IEEE 802.15.4g, 2dBi omni

<http://zolertia.io/>  
<https://ict-rerum.eu/first-long-range-test-with-the-rerum-re-mote-platform/>



Zolertia Z1 mote  
2.4Ghz, 284 m @250Kbps  
IEEE 802.15.4  
3dBi omni + 12dBi directional



> 1MB RAM/ROM

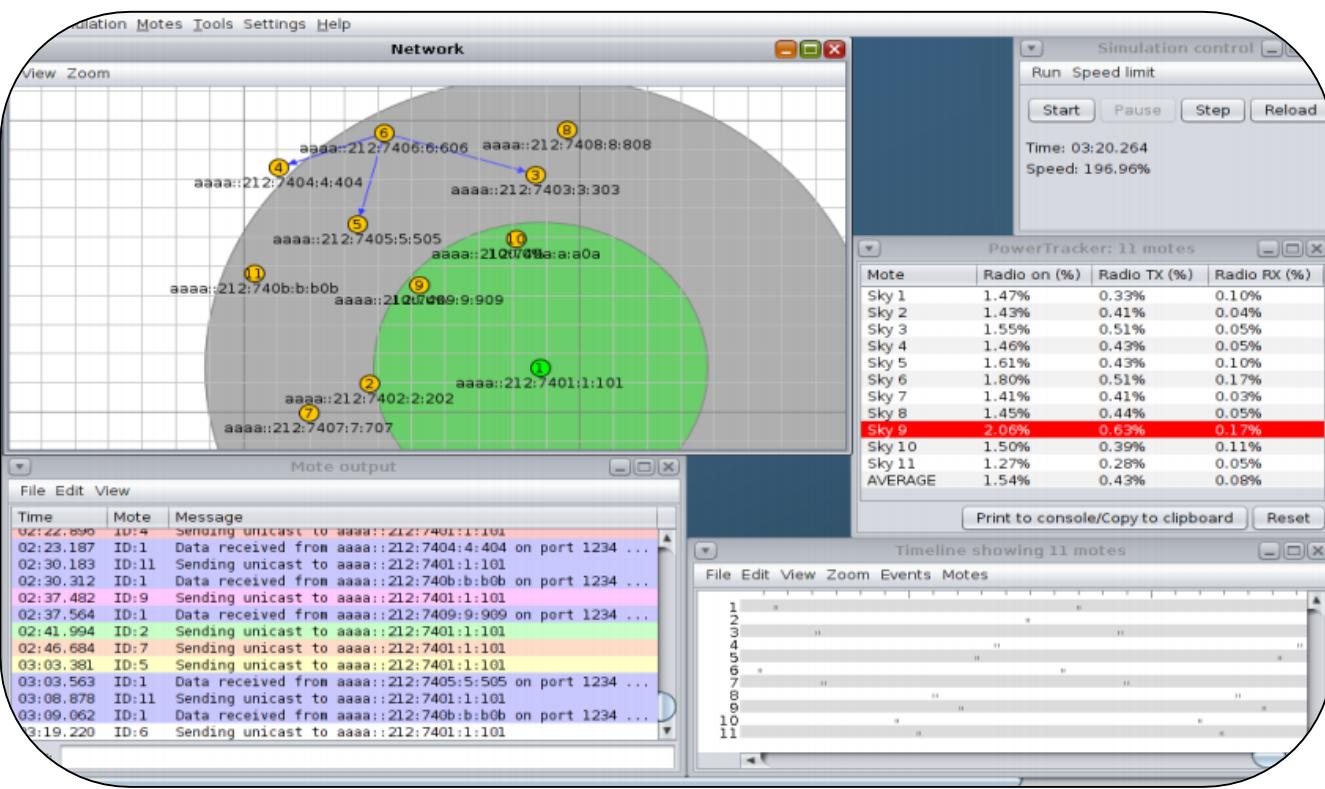
# Contiki

The Open Source OS for the Internet of Things

- Architectures: 8-bit, 16-bit, 32-bit
- Open Source (source code openly available)
- IPv4/IPv6/Rime networking
- Devices with < 8KB RAM
- Typical applications < 50KB Flash
- Vendor and platform independent
- C language
- Developed and contributed by Universities,  
Research centers and industry



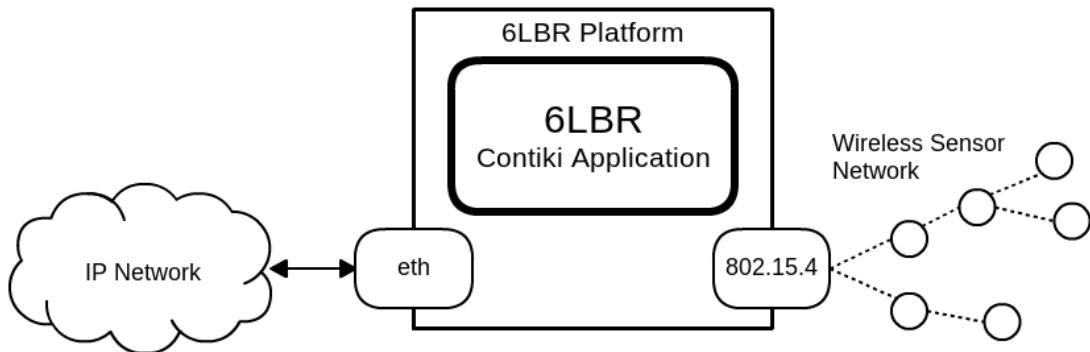




<http://www.tado.com>



<http://www.lifx.com>



<http://cetic.github.io/6lbr/>

 [contiki-os / contiki](#)

[Code](#) [Issues 117](#) [Pull requests 72](#) [Wiki](#) [Pulse](#) [Graphs](#)

The official git repository for Contiki, the open source OS for the Internet of Things <http://www.contiki-os.org/>

 11,147 commits  3 branches  16 releases  124 contributors

Branch: [master](#) [New pull request](#) [New file](#) [Upload files](#) [Find file](#) [HTTPS](#) <https://github.com/contiki>   [Download ZIP](#)

 alignan Merge pull request #1525 from Zolertia/remote-zonik ... Latest commit a3e13f1 2 days ago

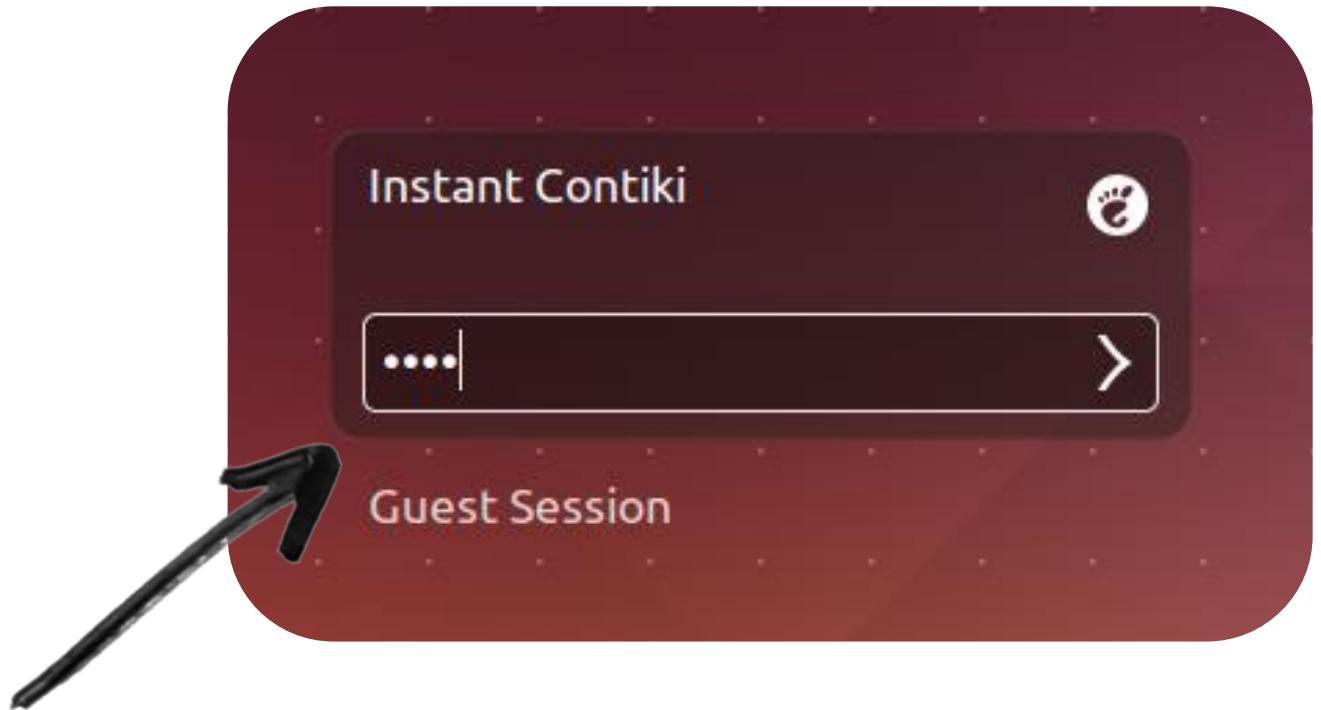


[www.contiki-os.org](http://www.contiki-os.org)

<https://github.com/contiki-os/contiki>

# INSTANT CONTIKI

VMWare virtualized develop environment



user

## If you are using a laptop/PC and have a 32-bit Linux machine

```
sudo add-apt-repository ppa:wireshark-dev/stable  
sudo apt-get -y install git git-core build-essential wireshark  
git clone -recursive https://github.com/alignan/contiki  
git checkout zolertia-tutorial
```

## To install the toolchain (application to convert the source code into an image to program the Zolertia devices)

```
wget "https://sourceforge.net/projects/zolertia/files/Toolchain/msp430-47.tar.gz" -O  
$HOME/msp430-47.tar.gz && tar -zvxf $HOME/msp430-47.tar.gz -C $HOME/msp430-47  
  
sudo echo "export PATH=$HOME/msp430-47/bin:$PATH" >> $HOME/.bashrc && source  
$HOME/.bashrc
```

**Virtual Network Editor**

Name	Type	External Connection	Host Connection	DHCP	Subnet Address
VMnet0	Bridged	Intel(R) Ethernet Connectio...	-	-	-
VMnet1	Host-only	-	Connected	Enabled	192.168.145.0
VMnet8	NAT	NAT	Connected	Enabled	192.168.229.0

**VMnet Information**

Bridged (connect VMs directly to the external network)

Bridged to: Intel(R) Ethernet Connection I218-LM

NAT (share host's IP address with VMs)

Host-only (connect VMs internally in a private network)

Connect a host virtual adapter to this network  
Host virtual adapter name: VMware Network Adapter VMnet0

Use local DHCP service to distribute IP address to VMs

Subnet IP:  Subnet mask:

 alignan	Added slides for day 2	Latest commit a8c2e47 just now
 apps	Reworked simple UDP rx/tx example, added binaries and made servreg-ha...	4 days ago
 core	MCU implementation (MSP430) Merge pull request #1293 from simonduq/pr/fix-warnings	6 days ago
 cpu	ring-free compilation even with fragmentation disabled	7 days ago
 dev	Devices implementation (radio, etc) (CC2420) king branch 'alignan/z1_sniffer' into walc15	5 days ago
 doc	Add support for the CC13xx CPU	3 months ago
 examples	Examples (ipv6, Zolertia, etc)	19 hours ago
 platform	Platform specific implementation (Z1, Zoul)	a day ago
 regression-tests	Merge pull request #1293 from simonduq/pr/fix-warnings	7 days ago
 tools	Tools (flashing, emulation, visualization)	a day ago

 alignan	Added optional switch to compile for the Rpi	Latest commit f5ee9e0 a day ago
..		
 apps	Specific Z1 applications	is. The node-id.h file contains
 dev	Specific sensors and actuators drivers	3 years ago
 Makefile.common	Makefiles (where the platform specifies the files to use and include)	28 days ago
 Makefile.z1		a day ago
 Makefile.z1sp	Merges Z1SP into Z1 platform	a year ago
 README.z1sp	Merges Z1SP into Z1 platform	a year ago
 cfs-coffee-arch.h	Coffee no longer uses watchdog calls	5 years ago
 contiki-conf.h	Specific configuration for Contiki	17 days ago
 contiki-z1-main.c	Main Application, Z1 initialization when booting	2 months ago
 contiki-z1-platform.c	Removed all old RCS tags in the Contiki source tree. Those RCS tags a...	3 years ago
 node-id.c	Use the Z1 product ID as MAC/Node ID if no value is found in the XMEM	a year ago
 platform-conf.h	Specific platform configuration (pin-out, peripherals)	a year ago



Name	Modified	Size	Downloads / Week
<a href="#">Parent folder</a>			
README.txt	2015-11-28	1.5 kB	1
msp430-47-rpi.tar.gz	2015-11-28	129.7 MB	3
msp430-z1.tar.gz	2012-08-17	17.4 MB	2
msp430-47.tar.gz	2012-08-17	97.5 MB	4
msp430-46.tar.gz	2012-08-17	84.8 MB	1
msp430-gcc-4.4.5.tar.gz	2011-09-02	21.1 MB	5
Totals: 6 Items		350.4 MB	16



user@instant-contiki: ~/contiki

File Edit View Search Terminal Help

```
user@instant-contiki:~/contiki$ msp430-gcc --version
msp430-gcc (GCC) 4.7.0 20120322 (mspgcc dev 20120716)
Copyright (C) 2012 Free Software Foundation, Inc.
This is free software; see the source for copying conditions. There is NO
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.

user@instant-contiki:~/contiki$
```

# 01-basics



Fixes a problem related to being allowed to write to USB ports as the /dev/ttyUSB0 used to flash the nodes

```
sudo usermod -a -G dialout user
```

For the change to take effect, you need to logout and log back in

```
PROCESS(hello_world_process, "Hello world process"); ①
AUTOSTART_PROCESSES(&hello_world_process); ②
```

- ① `hello_world_process` is the name of the process and `"Hello world process"` is the readable name of the process when you print it to the terminal.
- ② The `AUTOSTART_PROCESSES(&hello_world_process)` tells Contiki to start that process when it finishes booting.

```
/*
PROCESS(hello_world_process, "Hello world process");
AUTOSTART_PROCESSES(&hello_world_process);
*/
PROCESS_THREAD(hello_world_process, ev, data) ①
{
    PROCESS_BEGIN(); ②
    printf("Hello, world\n"); ③
    PROCESS_END(); ④
}
```

- ① You declare the content of the process in the process thread. You have the name of the process and callback functions (event handler and data handler).
- ② Inside the thread you begin the process,
- ③ do what you want and
- ④ finally end the process.

To compile an application and program the nodes:

```
make TARGET=z1 hello-world.upload
```

You can save the TARGET so next time you don't have to type it:

```
make TARGET=z1 savetarget
```

This will create a `Makefile.target` file, for the compiler to know which platform to compile for, if no TARGET argument is added in the compilation command line

Shows a list of connected devices and USB ports

**make z1-motelist**

Restarts the devices

**make z1-reset**

Opens a serial connection and prints debug output

**make login**

As “make login” but with a timestamp

**make serialview**

If there are more than one device connected, use **MOTES=/dev/ttyUSBx** to choose which one to command, else the above commands will be executed on all connected devices

```
user@instant-contiki:~/contiki/examples/zolertia/tutorial/01-basics$ make TARGET=z1 01-hello-world.  
upload  
msp430-objcopy 01-hello-world.z1 -O ihex 01-hello-world.ihex  
cp 01-hello-world.ihex tmpimage.ihex  
/dev/ttyUSB0  
make z1-reset z1-upload  
make[1]: Entering directory '/home/user/contiki/examples/zolertia/tutorial/01-basics'  
make -k -j 20 z1-reset-sequence  
make[2]: Entering directory '/home/user/contiki/examples/zolertia/tutorial/01-basics'  
../../../../../tools/zolertia/z1-bsl-nopic --z1 -c /dev/ttyUSB0 -r  
MSP430 Bootstrap Loader Version: 1.39-goodfet-8  
Use -h for help  
Use --fromweb to upgrade a GoodFET.  
Reset device ...  
Done  
make[2]: Leaving directory '/home/user/contiki/examples/zolertia/tutorial/01-basics'  
make -j 20 z1-upload-sequence  
make[2]: Entering directory '/home/user/contiki/examples/zolertia/tutorial/01-basics'  
+++++ Erasing /dev/ttyUSB0  
MSP430 Bootstrap Loader Version: 1.39-goodfet-8  
Use -h for help  
Use --fromweb to upgrade a GoodFET.  
Mass Erase...  
Transmit default password ...  
+++++ Programming /dev/ttyUSB0  
MSP430 Bootstrap Loader Version: 1.39-goodfet-8  
Invoking BSL...  
Transmit default password ...  
Current bootstrap loader version: 2.13 (Device ID: f26f)  
Changing baudrate to 38400 ...  
Program ...  
43055 bytes programmed.  
+++++ Resetting /dev/ttyUSB0  
MSP430 Bootstrap Loader Version: 1.39-goodfet-8
```

```
x - □ user@instant-contiki: ~/contiki/examples/zolertia/tutorial/01-basics
File Edit View Search Terminal Help
user@instant-contiki:~/contiki/examples/zolertia/tutorial/01-basics$ 
user@instant-contiki:~/contiki/examples/zolertia/tutorial/01-basics$ 
user@instant-contiki:~/contiki/examples/zolertia/tutorial/01-basics$ make z1-motelist
using saved target 'z1'
../../../../tools/zolertia/motelist-zolertia -b z1
-----
Reference      Device          Description
-----
Z1RC5072        /dev/ttyUSB0    Silicon Labs Zolertia Z1
user@instant-contiki:~/contiki/examples/zolertia/tutorial/01-basics$ █
```

```
user@instant-contiki:~/contiki/examples/zolertia/tutorial/01-basics$ make z1-reset && make login
using saved target 'z1'
make -k -j 20 z1-reset-sequence
using saved target 'z1'
make[1]: Entering directory `/home/user/contiki/examples/zolertia/tutorial/01-basics'
../../../../../tools/zolertia/z1-bsl-nopic --z1 -c /dev/ttyUSB0 -r
MSP430 Bootstrap Loader Version: 1.39-goodfet-8
Use -h for help
Use --fromweb to upgrade a GoodFET.
Reset device ...
Done
make[1]: Leaving directory `/home/user/contiki/examples/zolertia/tutorial/01-basics'
using saved target 'z1'
../../../../../tools/sky/serialdump-linux -b115200 /dev/ttyUSB0
connecting to /dev/ttyUSB0 (115200) [OK]
Rime started with address 193.12.0.0.0.19.208
MAC c1:0c:00:00:00:13:d0 Ref ID: 5072
Contiki-2.6-3253-g441f988 started. Node id is set to 5072.
CSMA ContikiMAC, channel check rate 8 Hz, radio channel 26
Tentative link-local IPv6 address fe80:0000:0000:c30c:0000:0000:13d0
Starting 'Hello world process'
Hello, world
Hello world, again!
This is a value in hex 0xABCD, the same as 43981
```

# Buttons and LEDs

Events and actions can be triggered by pressing the user button: send a message over the radio, take a sensor sample, start a process, etc.

The LEDs (light-emitting diodes) help us to understand what happens in the mote, by using different colours and blinking sequences we know when an event is happening, if there are any errors or what happens in our application.

```

PROCESS_THREAD(led_button_process, ev, data)
{
    /* Every process start with this macro, we tell the system this is the start
     * of the thread
     */
    PROCESS_BEGIN();

    /* Start the user button using the "SENSORS_ACTIVATE" macro */
    SENSORS_ACTIVATE(button_sensor);

    /* And now we wait for the button_sensor process to inform us about the user
     * pressing the button. We create a loop to wait forever, but to save
     * processing cycles, we "pause" the application until the expected event is
     * received and only resume when this event occurs
     */

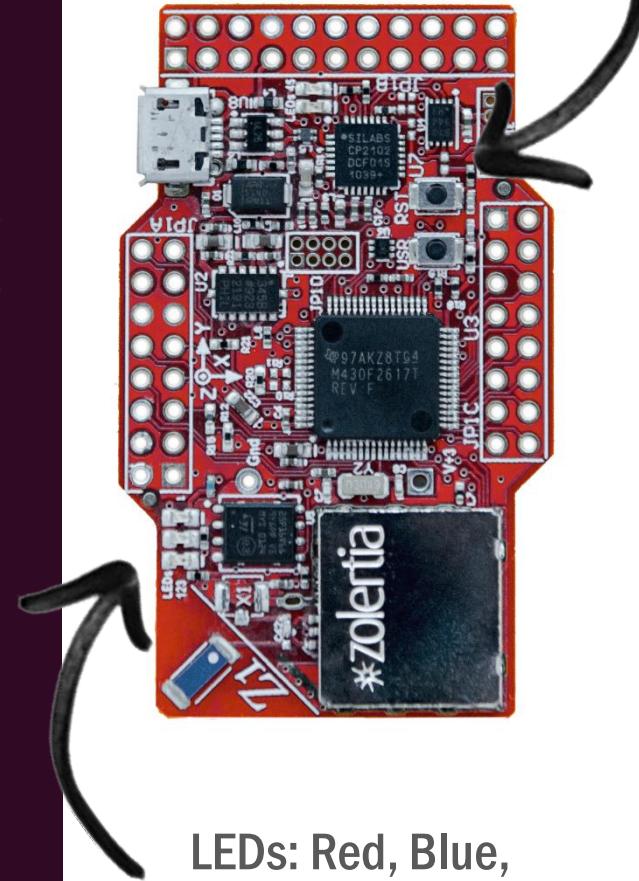
    while(1) {
        printf("Press the User Button\n");
        PROCESS_WAIT_EVENT_UNTIL(ev == sensors_event && data == &button_sensor);

        /* When the user button is pressed, we toggle the LED on/off... */
        leds_toggle(LEDs_GREEN);

        /* To try different LED combinations try and replace "LEDs_GREEN" with:
         * - LEDs_RED
         * - LEDs_BLUE
         * - LEDs_ALL
         *
         * And we print its status: when zero the LED is off, else on.
         * The number printed when the sensor is on is the LED ID, this value is
         * used as a mask, to allow turning on and off multiple LED at the same
         * time (for example using "LEDs_GREEN + LEDs_RED" or "LEDs_ALL"
         */
        printf("The sensor is: %u\n", leds_get());
    }
}

```

## Buttons: User & Reset



## LEDs: Red, Blue, Green

# Timers

Timers allow to execute actions periodically, like measuring a sensor periodically, waiting a few seconds before executing a function, etc.



```

static void
rtimer_callback_example(struct rtimer *timer, void *ptr)
{
    uint32_t *rtimer_ticks = ptr;
    printf("rtimer, now: \t%ld\n", *rtimer_ticks);

    /* We can restart the ctimer and keep the counting going */
    (*rtimer_ticks)++;
    ctimer_restart(&ct);
}
/*-----*/
/* This is an example of functions called by the ctimer callback timer. Notice
 * the argument of the function is "void *ptr", meaning you can pass any type
 * of data as pointer
 */
static void
ctimer_callback_example(void *ptr)
{
    uint32_t *ctimer_ticks = ptr;
    printf("ctimer, now: \t%ld\n", *ctimer_ticks);

    /* The real timer allows execution of real-time tasks (with predictable
     * execution times).
     * The function RTIMER_NOW() is used to get the current system time in ticks
     * and RTIMER_SECOND specifies the number of ticks per second.
     */
    (*ctimer_ticks)++;
    rtimer_set(&rt, RTIMER_NOW() + RTIMER_SECOND, 0,
              rtimer_callback_example, ctimer_ticks);
}

```

```

void etimer_set(struct etimer *t, clock_time_t interval); // Start the timer.
void etimer_reset(struct etimer *t); // Restart the timer from the previous expiration time
void etimer_restart(struct etimer *t); // Restart the timer from current time.
void etimer_stop(struct etimer *t); // Stop the timer.
int etimer_expired(struct etimer *t); // Check if the timer has expired.
int etimer_pending(); // Check if there are any non-expired event timers.
clock_time_t etimer_next_expiration_time(); // Get the next event timer expiration time.
void etimer_request_poll(); // Inform the etimer library that the system clock has changed.

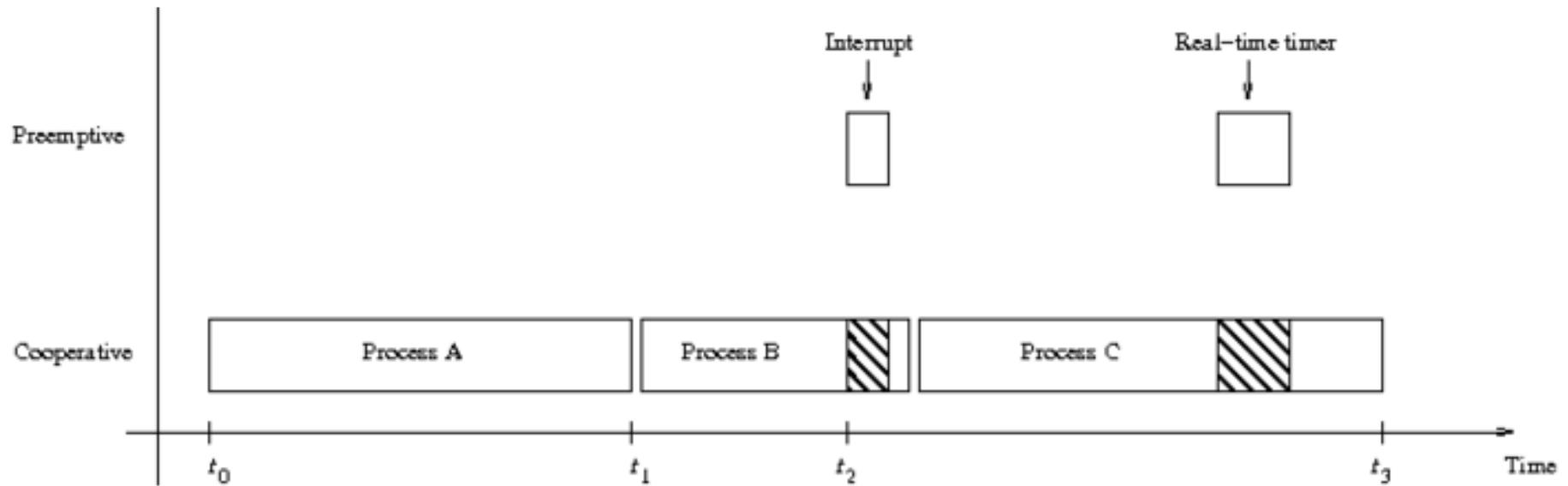
```

# Timers

- Timer: ms, manual
- Stimer: seconds, manual
- Etimer: ms, triggers an event
- Ctimer: ms, callbacks
- Rtimer: us, callbacks

# Processes

Contiki has two execution contexts: cooperative and preemptive  
Processes are cooperative and sequential, interrupts (button, sensors events) and the real-timer are preemptive.



```

printf("Process 1 started\n");

/* Use a random value to wait before starting the process */
etimer_set(&et1, WAIT_TIME);
PROCESS_WAIT_EVENT_UNTIL(etimer_expired(&et1));

/* Start the process and send as data our name */
process_start(&process3, "Process 1");

/* And wait until process3 sends us a message */

while(1) {
    /* This protothread waits for any event, we need to check of
     * ourselves
    */
    PROCESS_YIELD();

    /* We are waiting here for an event from process3 */
    if(ev == event_from_process3) {
        counter = *((uint8_t *)data);
        printf("Process 3 has requested shutdown in %u seconds\n", counter);
        etimer_set(&et1, CLOCK_SECOND);
    }

    /* We are waiting here for a timer event */
    if(ev == PROCESS_EVENT_TIMER) {

        /* When the counter reaches zero, kill process3 */
        if(counter <= 0) {
            process_exit(&process3);

        /* Increment the counter value and restart the timer */
        } else {
            printf("Process 3 will be terminated in: %u\n", counter);
            counter--;
            leds_toggle(LEDS_RED);
            etimer_reset(&et1);
        }
    }
}

```

```

struct process {
    struct process *next;
    const char *name;
    int (* thread)(struct pt *,
                    process_event_t,
                    process_data_t);
    struct pt pt;
    unsigned char state, needspoll;
};

```

# Sensors

A sensor is a transducer whose purpose is to sense or detect a characteristic of its environment, providing a corresponding output, generally as an electrical or optical signal, related to the quantity of the measured variable

```

/* Initialize the sensors, the SENSORS_ACTIVATE(...) macro invokes the
 * configure(...) method of Contiki's sensor API
 */
SENSORS_ACTIVATE(adxl345);
SENSORS_ACTIVATE(tmp102);
SENSORS_ACTIVATE(battery_sensor);

/* Spin the timer */
etimer_set(&et, CLOCK_SECOND);

while(1) {

    PROCESS_WAIT_EVENT_UNTIL(etimer_expired(&et));

    /* Read the sensors */
    x_axis = adxl345.value(X_AXIS);
    y_axis = adxl345.value(Y_AXIS);
    z_axis = adxl345.value(Z_AXIS);
    temp   = tmp102.value(TMP102_READ);
    batt   = battery_sensor.value(1);

    /* Print the readings */
    printf("Acceleration: X %d Y %d Z %d\n", x_axis, y_axis, z_axis);
    printf("Temperature: %d.%u\n", temp / 100, temp % 100);

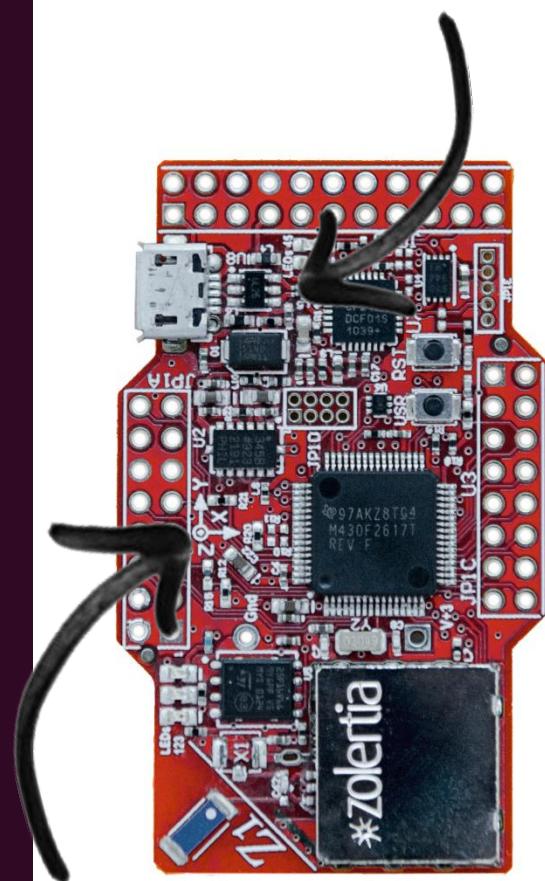
    /* Convert the ADC readings to mV */
    batt *= 5000;
    batt /= 4095;
    printf("Battery: %u\n\n", (uint16_t)batt);

    etimer_reset(&et);
}

PROCESS_END();

```

TMP102: temperature



ADXL345: acceleration(3 axis)



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github.com/alignan



hackster.io/alinan