

# Powering Issues

Abdus Salam ICTP, February 2006

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# Powering Issues

Agenda:

Grounding and Bonding

Power faults

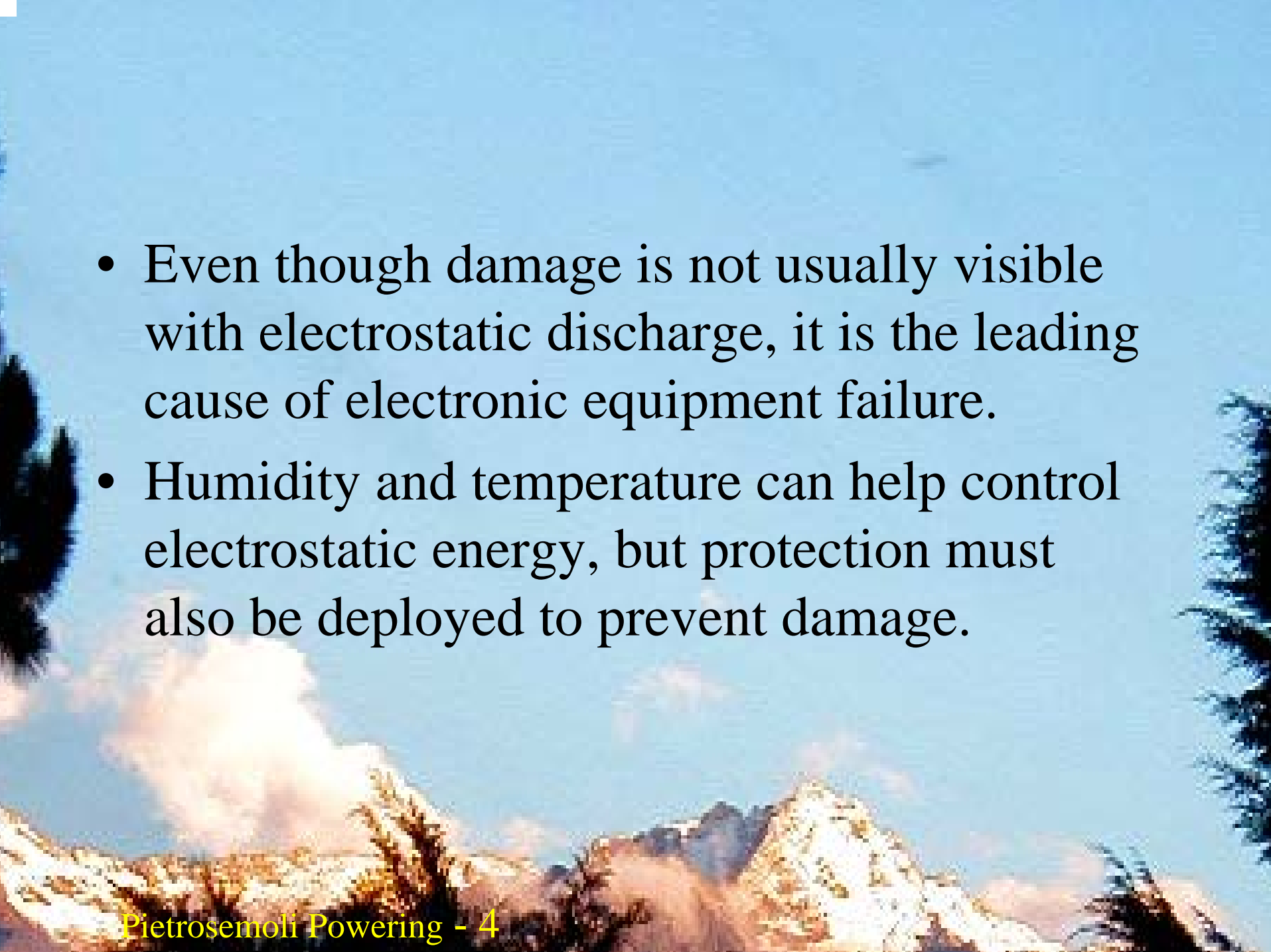
Power over Ethernet

Solar and Wind Power

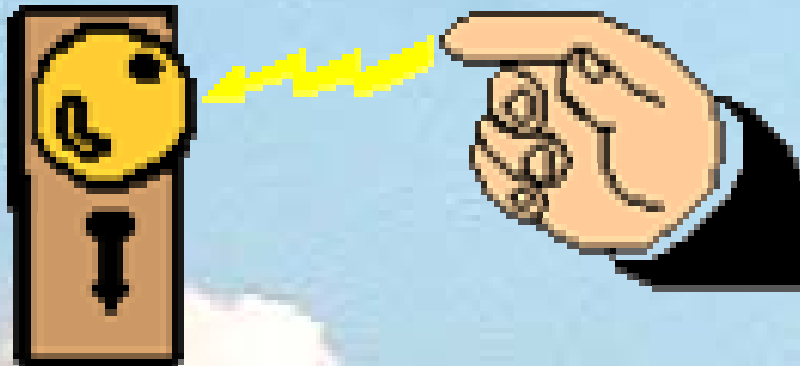
# Grounding & Bonding

## Reasons for Grounding

- Personnel safety
- Protection from high voltages
  - Lightning
  - Power faults
- Dissipate electrostatic charges
- Provide a zero volt reference
- Protection of electronic equipment
- Reduction of noise and interference

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- Even though damage is not usually visible with electrostatic discharge, it is the leading cause of electronic equipment failure.
  - Humidity and temperature can help control electrostatic energy, but protection must also be deployed to prevent damage.

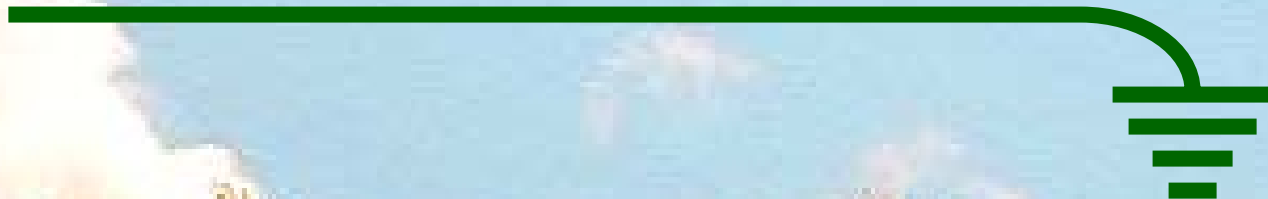
# Electrostatic Discharge



- Caused when current passes from one object to another.
- Usually high voltage, but low current.
- A typical 1 cm electrostatic arc from a finger to a doorknob is around 19,000 Volts!

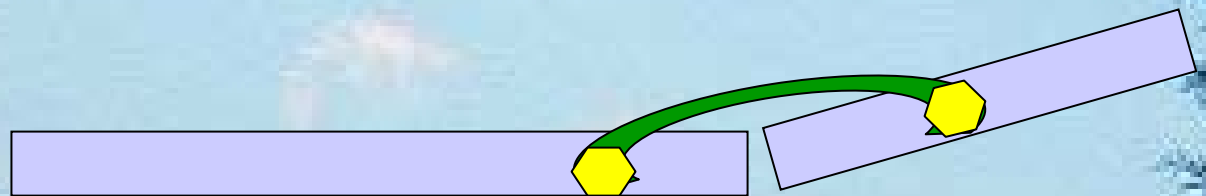
# Grounding & Bonding

- “**Ground**: A conducting connection, whether intentional or accidental, between an electrical circuit or equipment and the earth, or to some conducting body that serves in place of the earth.”



# Grounding & Bonding

- “**Bonding** (Bonded). The permanent joining of metallic parts to form an electrically conductive path that will ensure electrical continuity and the capacity to conduct safely any current likely to be imposed.”
- Effective bonding helps equalize potentials.



# Grounding & Bonding

- Grounding in a cabling installation refers to connecting non-current carrying metal parts of conduits, raceways, conductors and electrical equipment to a building's system ground.



# **Ground Resistance Objectives**

**National Electric Code (USA):**

**25 Ohms (Safety)**

**Equipment Manufacturers:**

**< 5 Ohms (Usually)**

## Conductor Surface Area

The most effective material for a ground system is copper strap. Copper as a metal is a good electrical conductor, only moderately attacked by ground and air borne acids, and should have a life-span measured in years.

Since lightning has a large portion of its energy in the RF range, it will behave like an RF signal. That means the energy will only be conducted on the skin of the conductor (skin effect). Such currents following a round-member conductor will not make extensive use of its large cross sectional area. With a 1-1/2 inch (38 mm) or larger flat strap of at least 26 gauge (0.41 mm), both surfaces will conduct the surge.

## Soil Doping

The earth is a conductor because of the number of ionic salts present in the soil. Conductivity can be improved by adding more ions to the soil.

Soil doping can be done by either adding water or a saline solution to the soil around the grounding system. If the soil already has a sufficient amount of naturally occurring salts, adding water will free the ions and improve conductivity.

If few natural ions are available, salts, such as Epsom salts, can be added to the soil to increase the conductivity.

Depending on the amount of rainfall, doping the ground system radials with 10 kg of salt per per rod may last approximately two years.

# Electrolytic Potential of Metals

Metal	Potential, V
• Aluminum	+1.67
• Zinc	+0.76
• Chromium	+0.71
• Iron	+0.44
• Cadmium	+0.40
• Nickel	+0.25
• Tin	+0.14
• Lead	-0.13
• Copper	-0.34
• Silver	-0.80
• Gold	-1.86



From: Physical Design of Yagi Antennas. David Leeson, American Radio Relay League, ARRL, 1992

# Grounding & Bonding

## Grounding System Components

The two areas of grounding that pertain to telecommunications equipment are the:

- Grounding electrode system (earthing system)
- Equipment grounding system (safety ground)

# Metal Corrosion

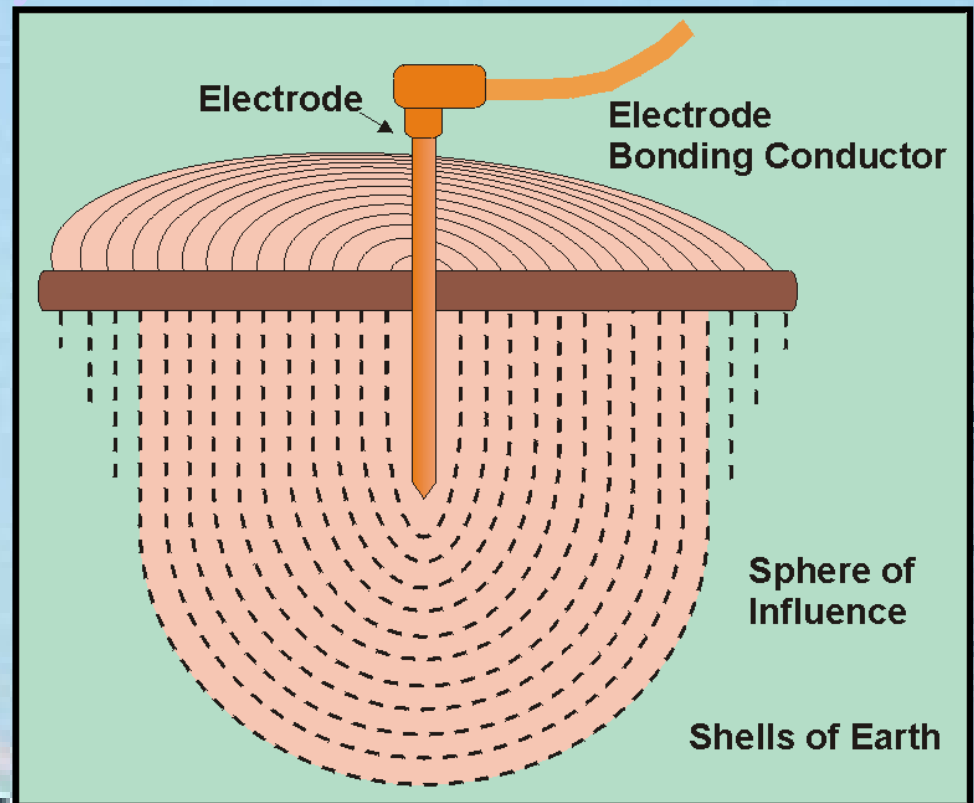
- To minimize electrolytic corrosion when two different metals are in moist contact their electrolytical potential should be as close as possible.
- Avoid attaching brass (which contains copper) to aluminum because their electrolytic potential difference is 2.01 V
- In the presence of oxygen, the zinc of galvanized steel sacrifices itself before the steel corrodes, since zinc is more negative than iron

# Grounding & Bonding

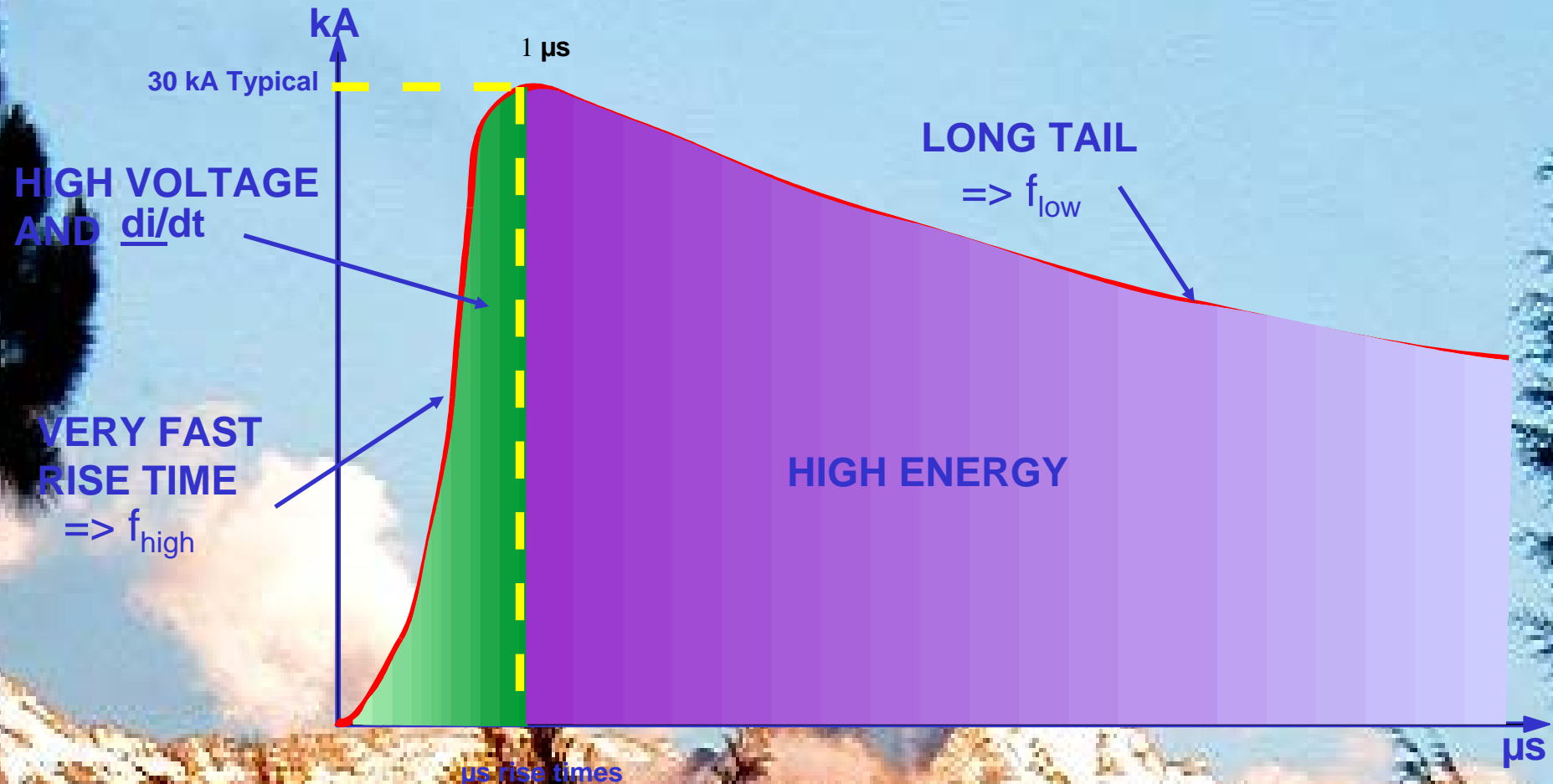
## Grounding System Components

The grounding electrode system consists of a:


- Grounding field (earth)
- Grounding electrode
- Grounding electrode conductor



# TYPICAL CHARACTERISTICS OF LIGHTNING IMPULSE







Instantaneous Power	Over one Megawatt
Total Energy	Over 250 Kilojoules
Sound Pressure	90 Atmospheres at 500m away
Temperature	30,000°K+ (5 times Sun Surface)
Rise Time	0.1 to 5 Microseconds
Average Current	30 kA
Duration	300 Microseconds + Repeats
Channel Length	5 km

# Grounding Electrode System

## Grounding Electrode:

- Metallic conductor (e.g., rod 17 mm in diameter), pipe (19 mm diameter) at least 2.4 m long, plate, ring, or other metallic object) in contact with the earth used to establish a low resistance current path to earth

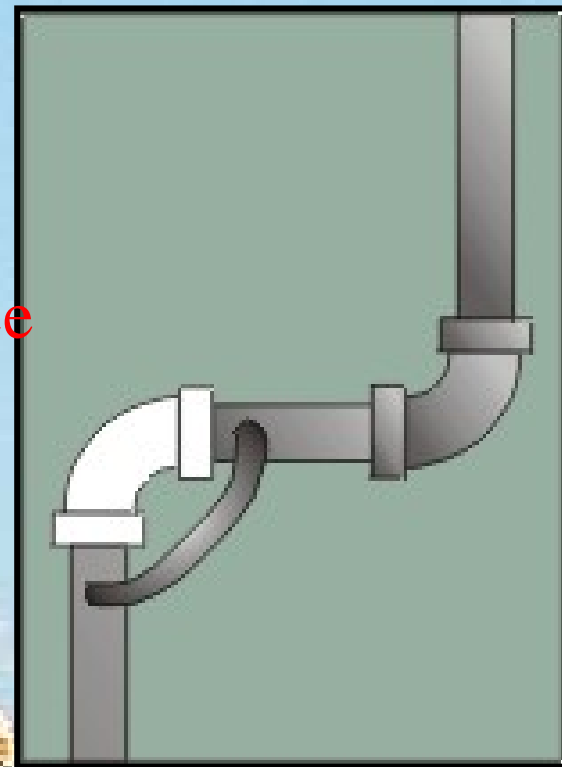
## Grounding Electrode System:

- Network of electrically connected ground electrodes used to achieve an improved low resistance to earth

# Grounding & Bonding

## Cold Water Pipes

- Historically the first choice
- Provides low resistance to earth
- Must be:
  - In direct contact with 3 m of earth
    - Bonded within 1.5 m of entrance
  - Electrically continuous
    - No plastic pipes or couplers—  
bond across discontinuities
  - Bonded to a second electrode type



# Grounding & Bonding

## Cold Water Pipes

### Advantages:

- Most homes have water
- Easily accessible
- Usually less than 3  $\Omega$  resistance to earth

# Grounding & Bonding

## Cold Water Pipes

### Disadvantages:

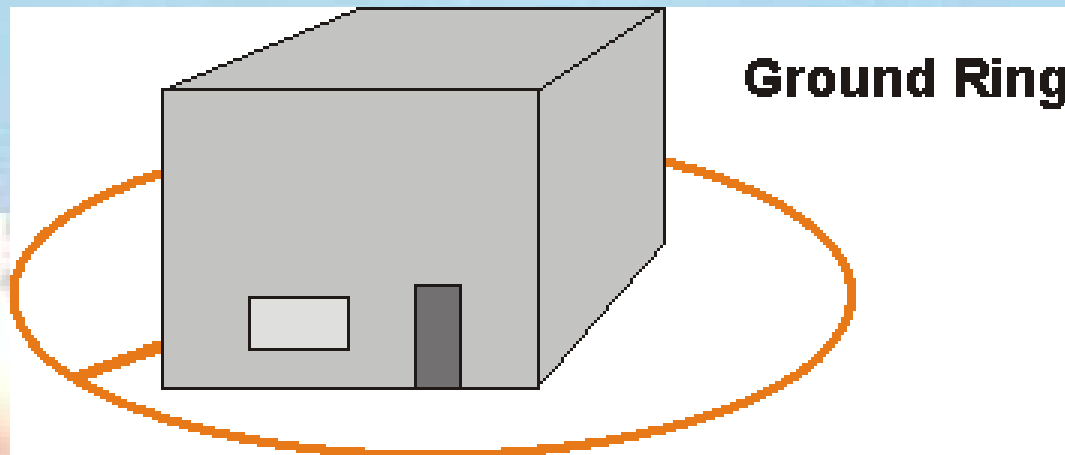
- Future repairs may be plastic
- Many cities use PVC
- Bonding causes electrolysis of the installed metallic pipes, causing reduced expected life span
  - Many cities are installing isolation joints made of PVC to separate their systems

# Grounding & Bonding

## Installing a Ground Ring

**Non-insulated conductors buried in the shape of a ring:**

- Buried a minimum depth of 76 cm
- Minimum size 2 AWG (7.91 mm) and 6 m in length

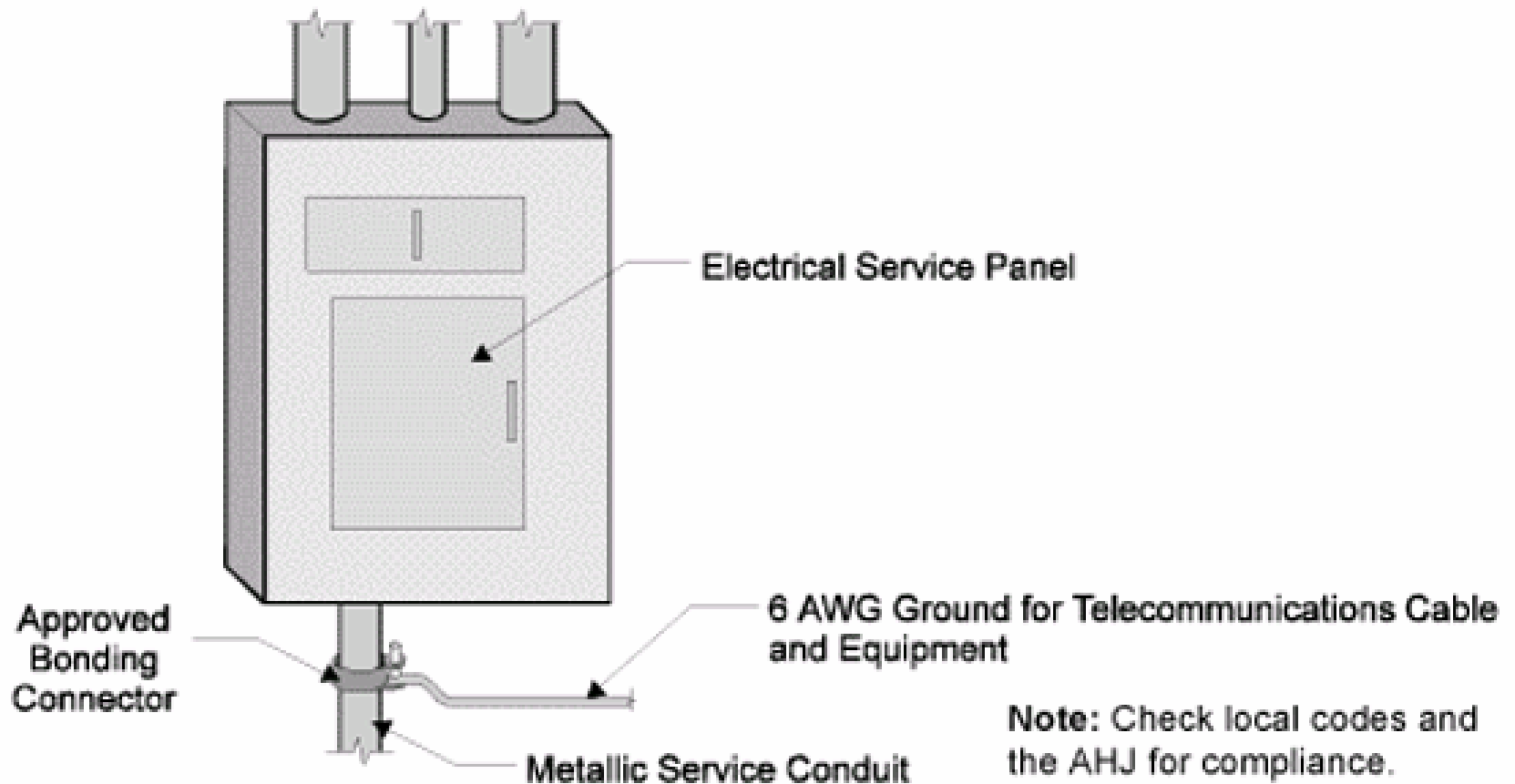


## Ground Radials

Radials are the most cost effective grounding technique considering system impedance, material cost, and installation labor. If one radial gives “X” resistance, then two will deliver an equivalent “parallel rule” plus 10%.

Radials do have a limit on their effective length. If the surge energy has not been launched into the soil within the first 22 m, the inductance of the radial will prevent any further effective proration. Therefore, as a general rule of thumb, all radials should be at least 15 m long and no longer than 23 m.

# Grounding & Bonding

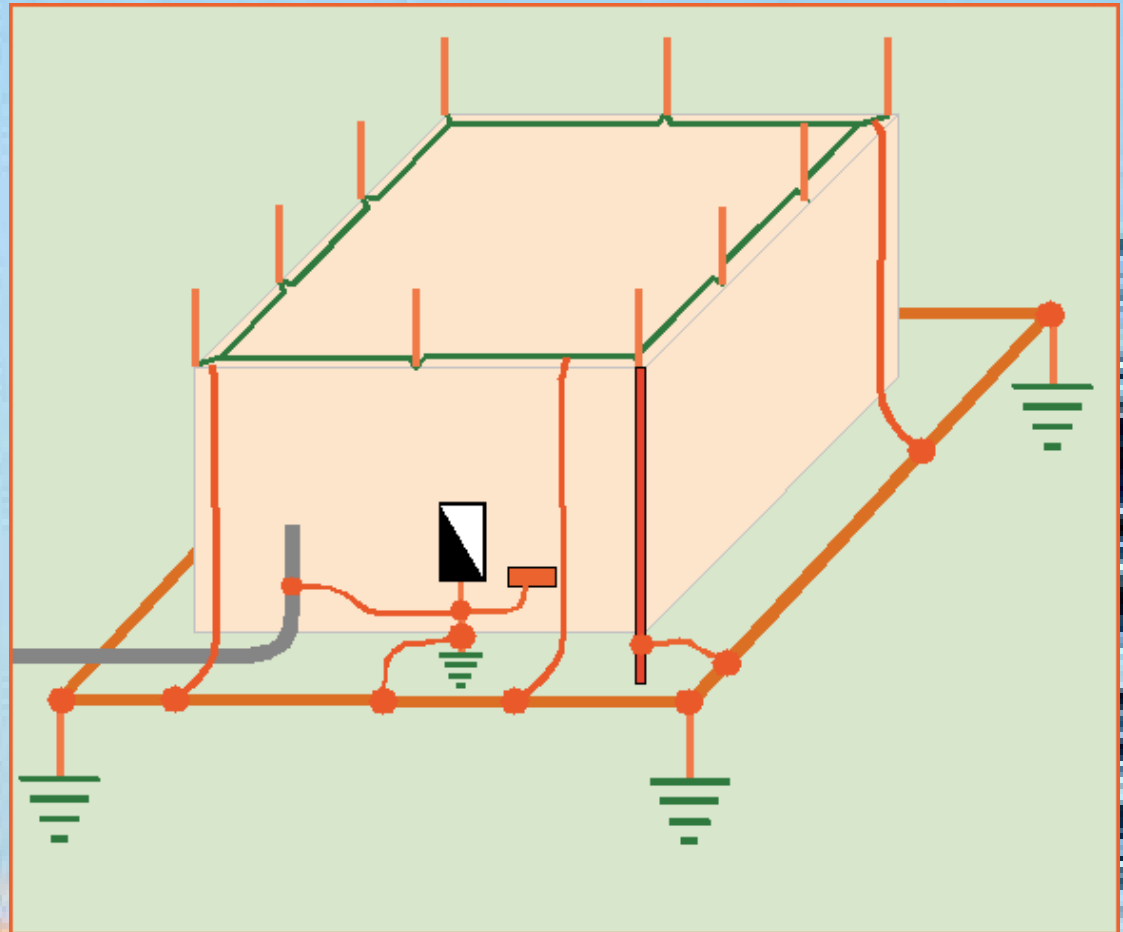




# Grounding & Bonding

Safety

All systems bonded

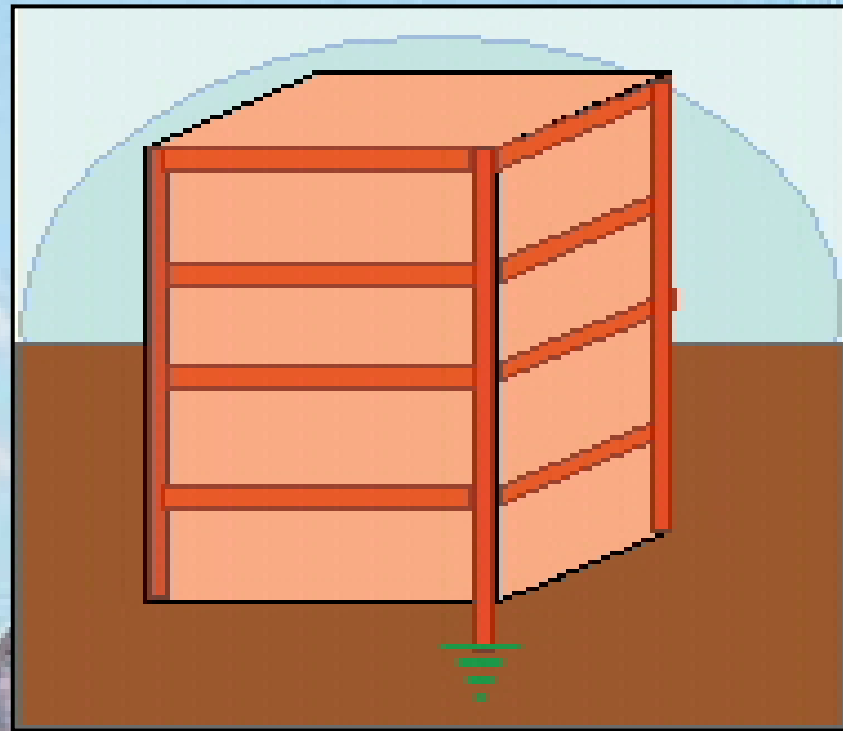


# Grounding & Bonding

## Building Steel

Usually a very good electrode

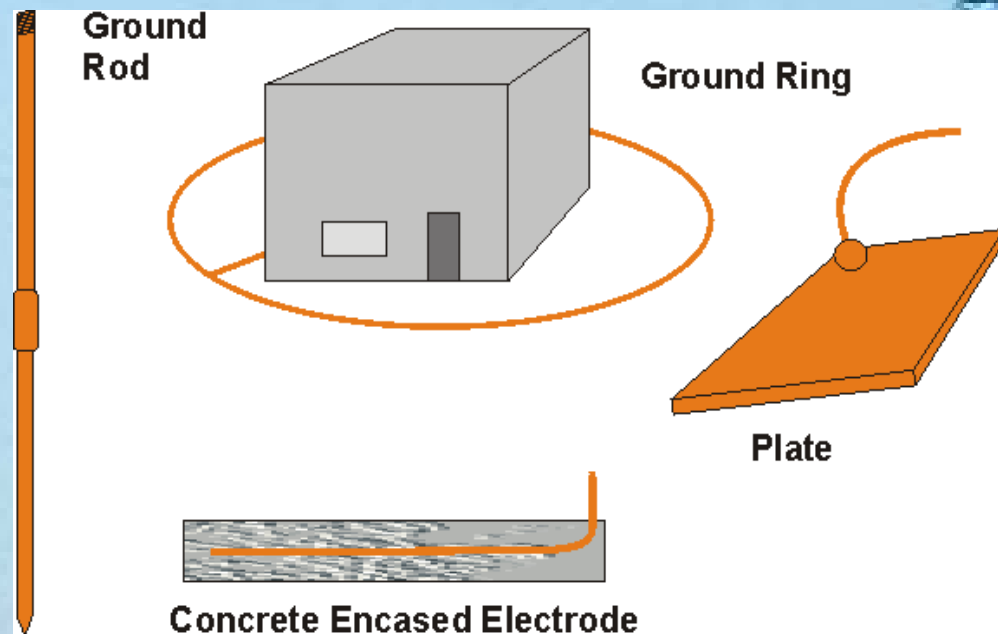
- Large physical size provides low impedance to earth
- Not always bonded together



# Grounding & Bonding

Electrodes specifically designed and installed for grounding:

- Buried ground rods
- Buried ground rings
- Buried metal plates
- Concrete encased electrodes
- Chemical ground rods



# Grounding & Bonding

- Generally speaking, "earth resistance" is the resistance of soil to the passage of electrical current
- The earth is a relatively poor conductor of electricity compared to normal conductors like copper wire. But, if the path for current is large enough, the resistance can be quite low and earth can be a good conductor

# Grounding & Bonding

Several factors can affect the resistance:

- Moisture content of the soil
- Quantity of electrolytes
- Type of electrolytes
- Adjacent conductors
- Temperature
- Electrode depth
- Electrode diameter
- Electrode(s) spacing distance

# Grounding & Bonding

## Resistivities of Different Soils

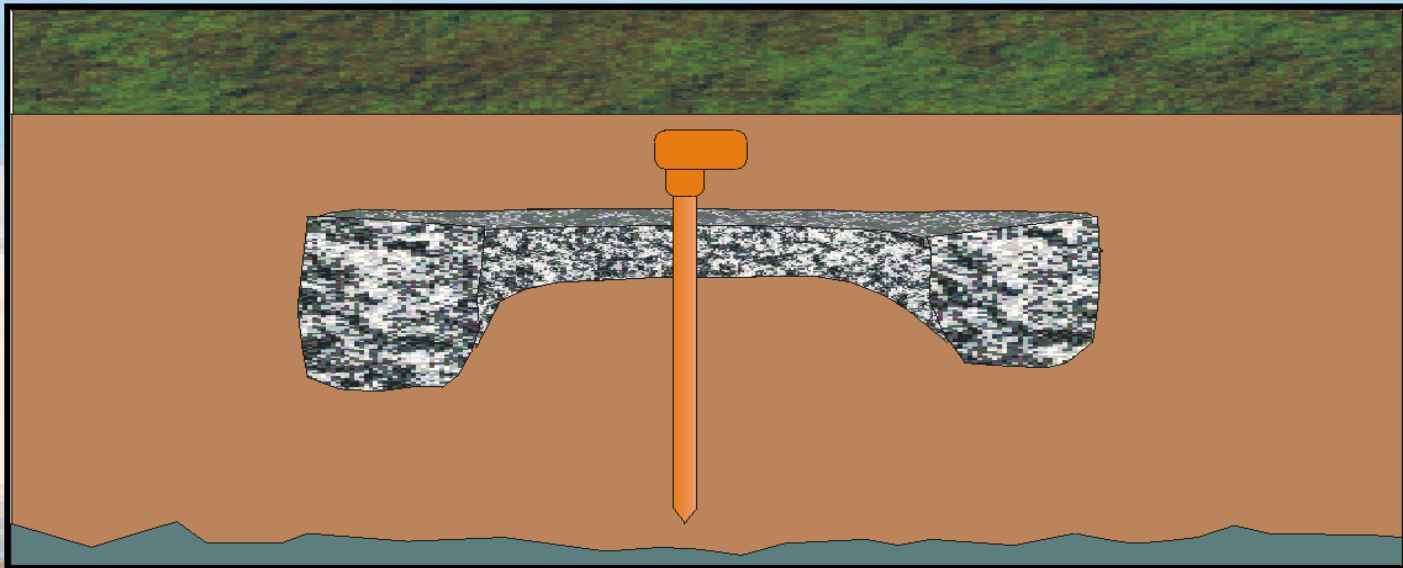
<b>Soil</b>	<b>Resistivity Ohm-CM (Range)</b>
Surface soils, loam, etc.....	100 - 5,000
Clay.....	200 - 10,000
Sand and gravel.....	5,000 - 100,000
Surface limestone.....	10,000 - 1,000,000
Limestones.....	500 - 400,000
Shales.....	500 - 10,000
Sandstone.....	2,000 - 200,000
Granites, basalts, etc.....	100,000
Decomposed gneisses.....	5,000 - 50,000
Slates, etc.....	1,000 - 10,000

\* Evershed & Vignoles Bulletin 245

# Grounding & Bonding

## Chemical treatment of the soil

- Used when longer rods can't be installed—bedrock
- Provides uniform ground through seasonal changes



# Ground Coils and Pigtails

- Coils and pigtails introduce an inductance to the ground path.
- Inductance doesn't like changes in current.

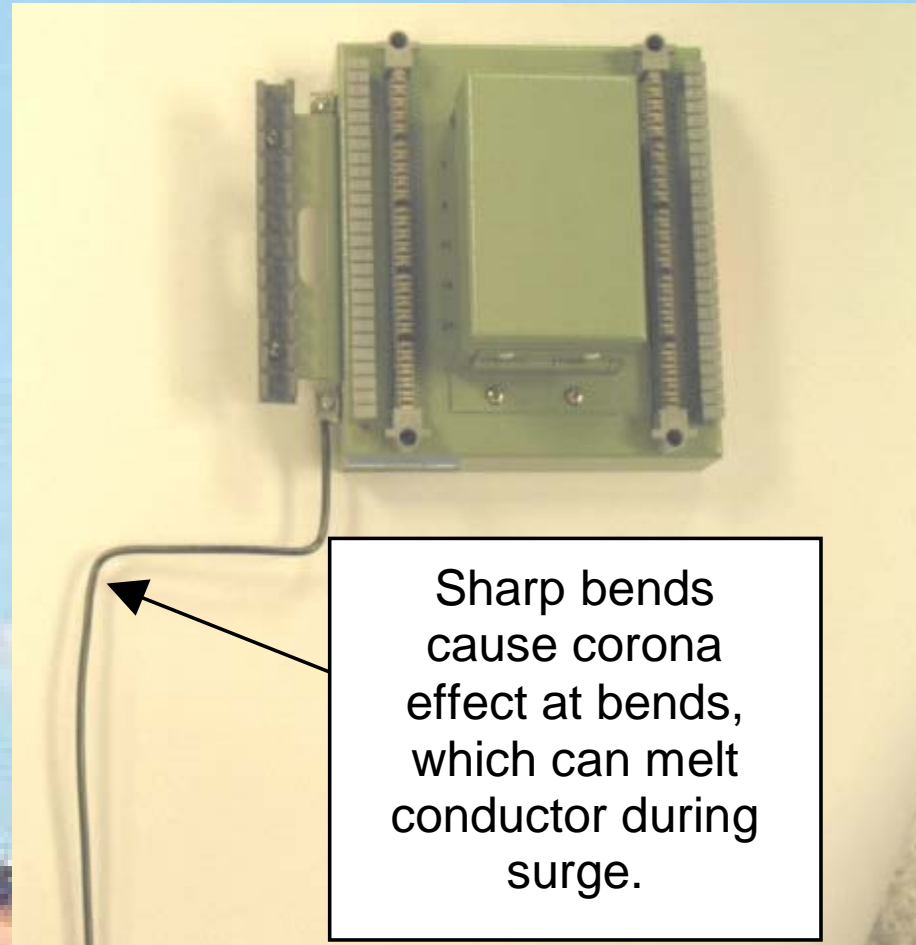
If there is inductance, then a surge might find it easier to go through the equipment versus the now restrictive ground path.



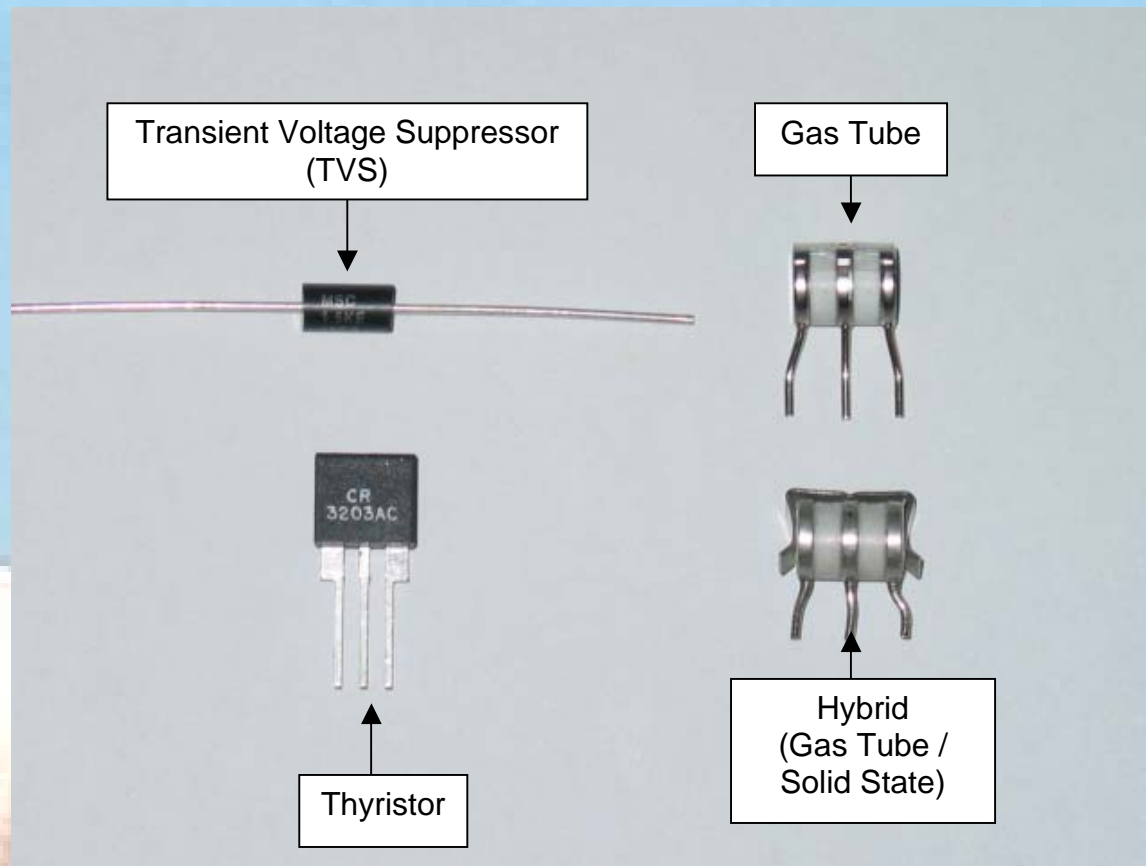
Avoid sharp bends. Corona effect at the bends will cause the wire to heat and melt.

Coils and pigtails introduce an inductance to the ground path.

If there is inductance, then a surge might find it easier to go through the equipment versus the now restrictive ground path.



# Lightning Arrestor Components



# Ground Antenna Mast

It is recommended that the antenna mast be grounded to either the building rooftop lightning ground system or to a separate earth ground system. The mast should be connected to the ground by a low resistance cable, size AWG #10 (3.43 mm diameter) copper or larger. Use suitable ground clamps to attach the cable to the mast and the ground system. Make sure the cable is making a good electrical connection, remove all paint and corrosion from the area the clamp attaches to. Use dielectric grease on the clamp connection to prevent any electrolysis activity due to dissimilar metals.

## Dissimilar Metals

Copper should never touch galvanized material directly without proper joint protection. Water shedding from the copper contains ions that will wash away the galvanized (zinc) tower covering. Stainless steel can be used as a buffer material. However, be aware that stainless steel is not a very good conductor. If it is used as a buffer between copper and galvanized metals, the surface area of the contact should be large and the stainless steel should be thin. Joint compound should also be used to cover the connection so water can not bridge between the dissimilar metals.

# Electrical Power Faults

## Types of Electrical System Faults

- Phase-to-phase faults
- Phase-to-neutral faults
- Phase-to-ground

Greater than 90% of electrical system faults will be phase-to-ground faults

- A phase-to-phase or phase-to-neutral fault will almost always trip the overcurrent device

# Electrical Power Faults

A phase-to-ground fault will not trip the overcurrent device if the impedance of the equipment grounding system is too high.

- The following factors govern equipment grounding conductor impedance:
  - Tightness of connections
  - Length
  - Proximity to circuit conductors during fault conditions
  - Number of bends and bend radius

# PoE

## Why Power Ethernet?

- Saves money and installation time
- More flexibility in the placing of devices
- Quite useful for outdoors install, allows for a long distance between the AP and the computer
- Does not require an electrician to install

# PoE Issues

- Standard or not
- End Span
- Mid Span
- Cat5e or Cat6 less than 25 ohm loop
- Pin assignment A or B
- Measured resistance for 10 m, 0.8 ohm
- Outdoor rated UTP Cable
- Signature



# **IEEE Std 802.3af-2003**

- **Powering Ethernet Devices through data cables**
- **Standard Titled: Data Terminal Equipment (DTE) Power via Media Dependent Interface (MDI)**
- **Approved June 2003**

# Standards terminology

## **IEEE**

– PSE

Power Source Equipment

– PD

Powered Device

-MDI

Media Dependent Interface (RJ45)

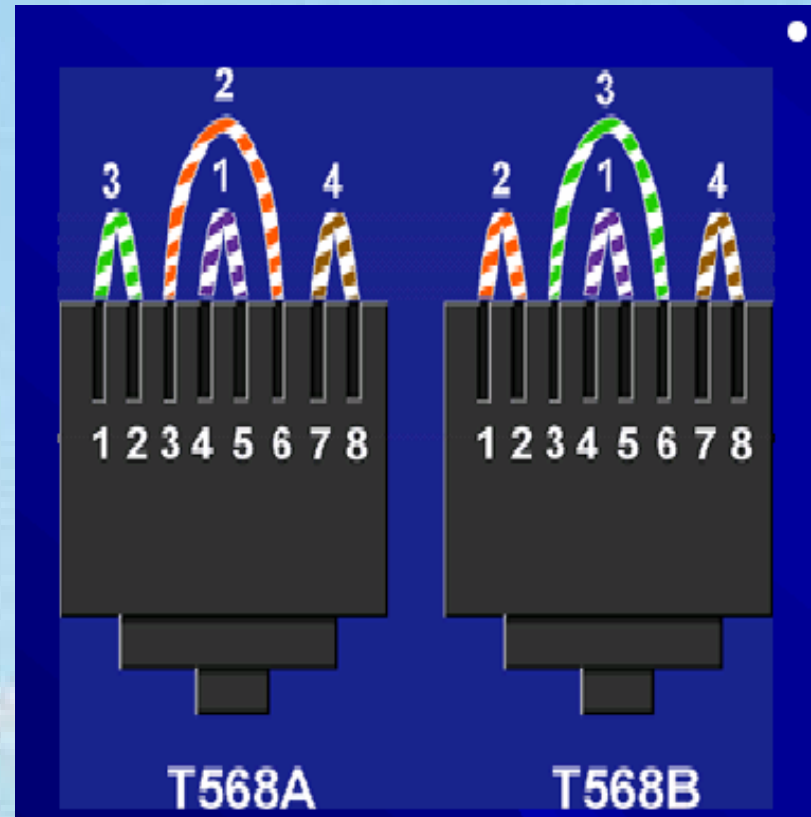
## **TIA/EIA**

– DCPS

DC Power Sourcing Equipment

– DCPL

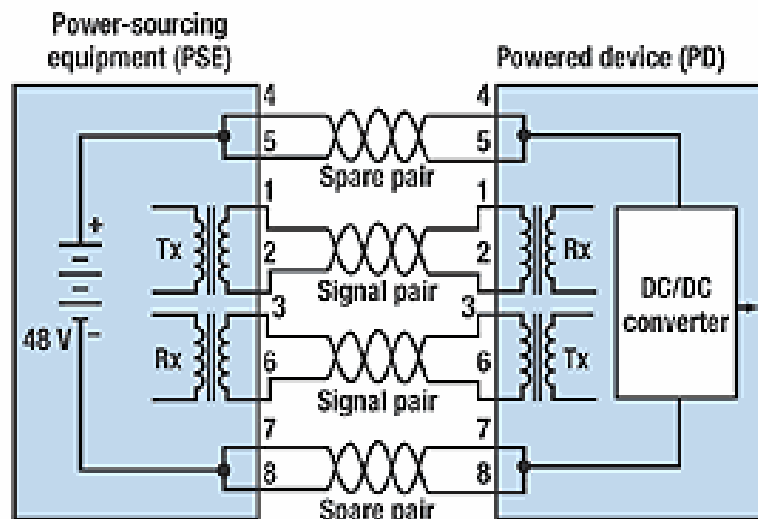
DC Power Load Equipment



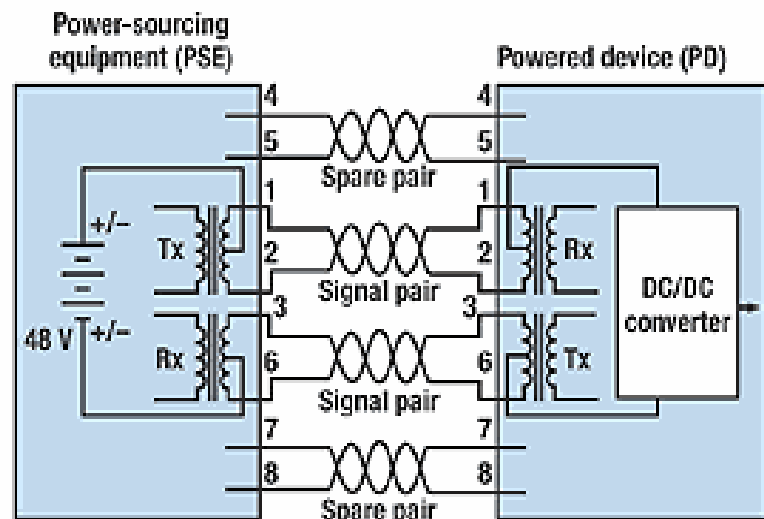
# End span or mid span

- PoE (802.3af) runs at 48VDC, with a max current of 350mA, capable of feeding a maximum load of 12.95W accounting for the cable losses
- End span 802.3af provides power on either the data pairs (1,2;3,6) or spare pairs (4,5;7,8), while "mid span" 802.3af provides power on the spare pairs (4,5;7,8).

# End span or mid span



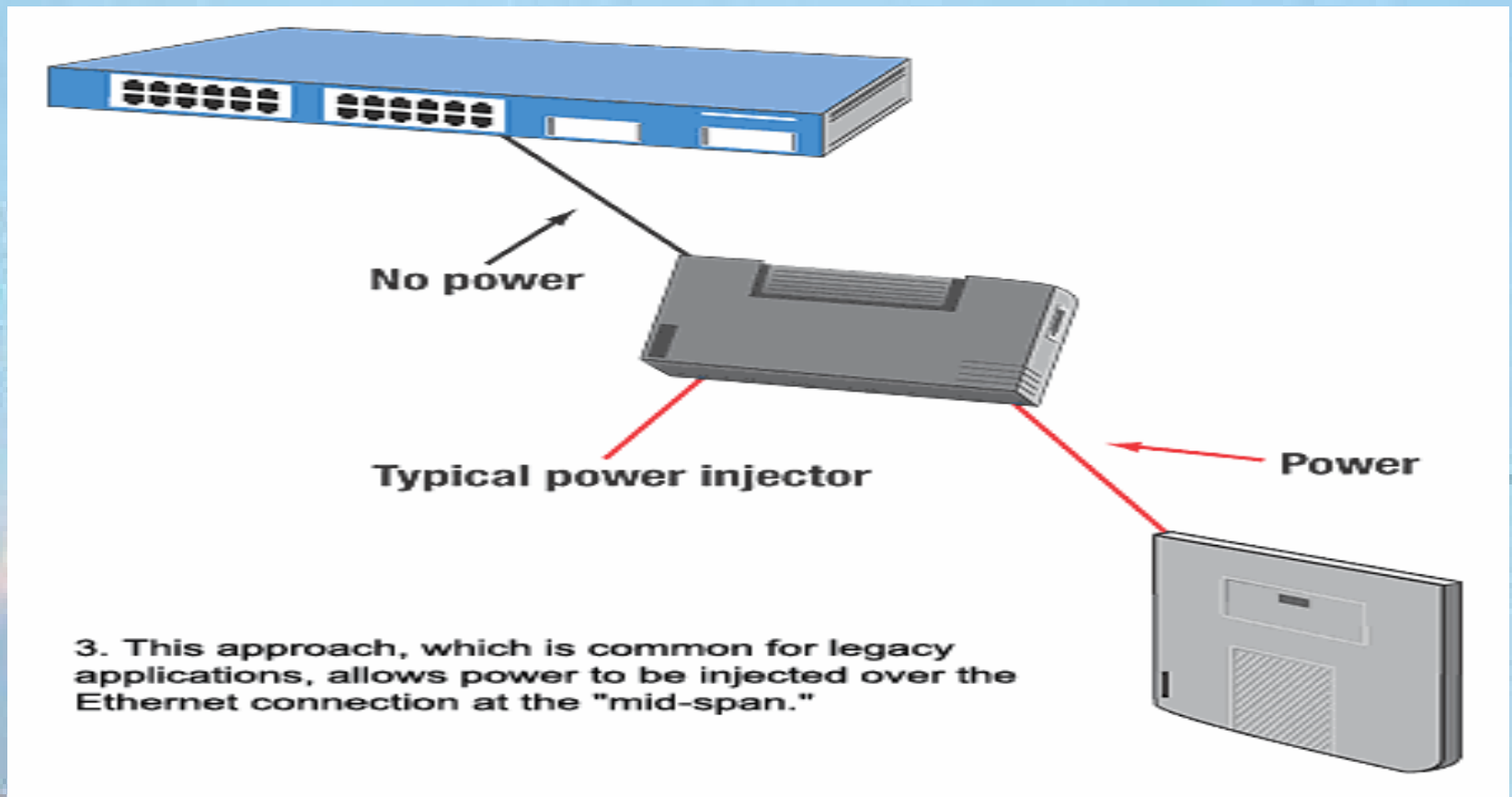
Configuration over spare pairs



Configuration over signal pairs

2. The power for Power-over-Ethernet devices can be supplied through the spare wires of a typical CAT-5 cable or by "floating" power over existing data-signal wire pairs. Both methods are supported by the standard.

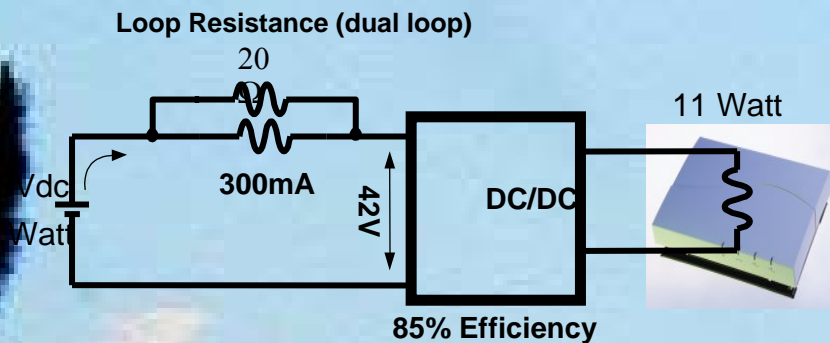
# Midspan Power



# Power over Ethernet

## Example 1

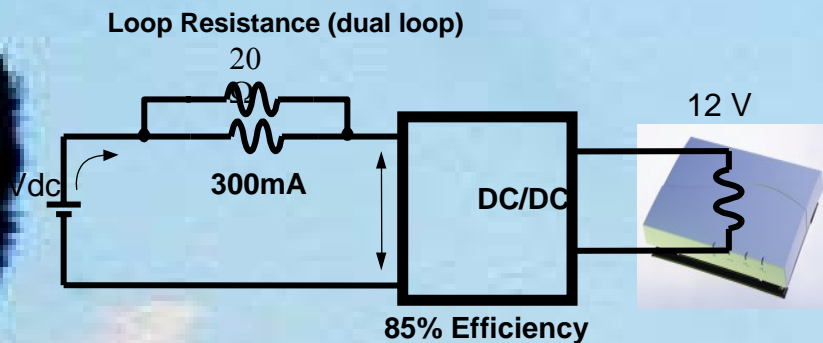
- Assuming:
- 48Vdc feeding
- 300mA continuous,
- Maximum 20 ohm loop resistance
- Delivering 48VDC Power over CAT 5 Spare Pairs (pins 4+5 & 7+8)



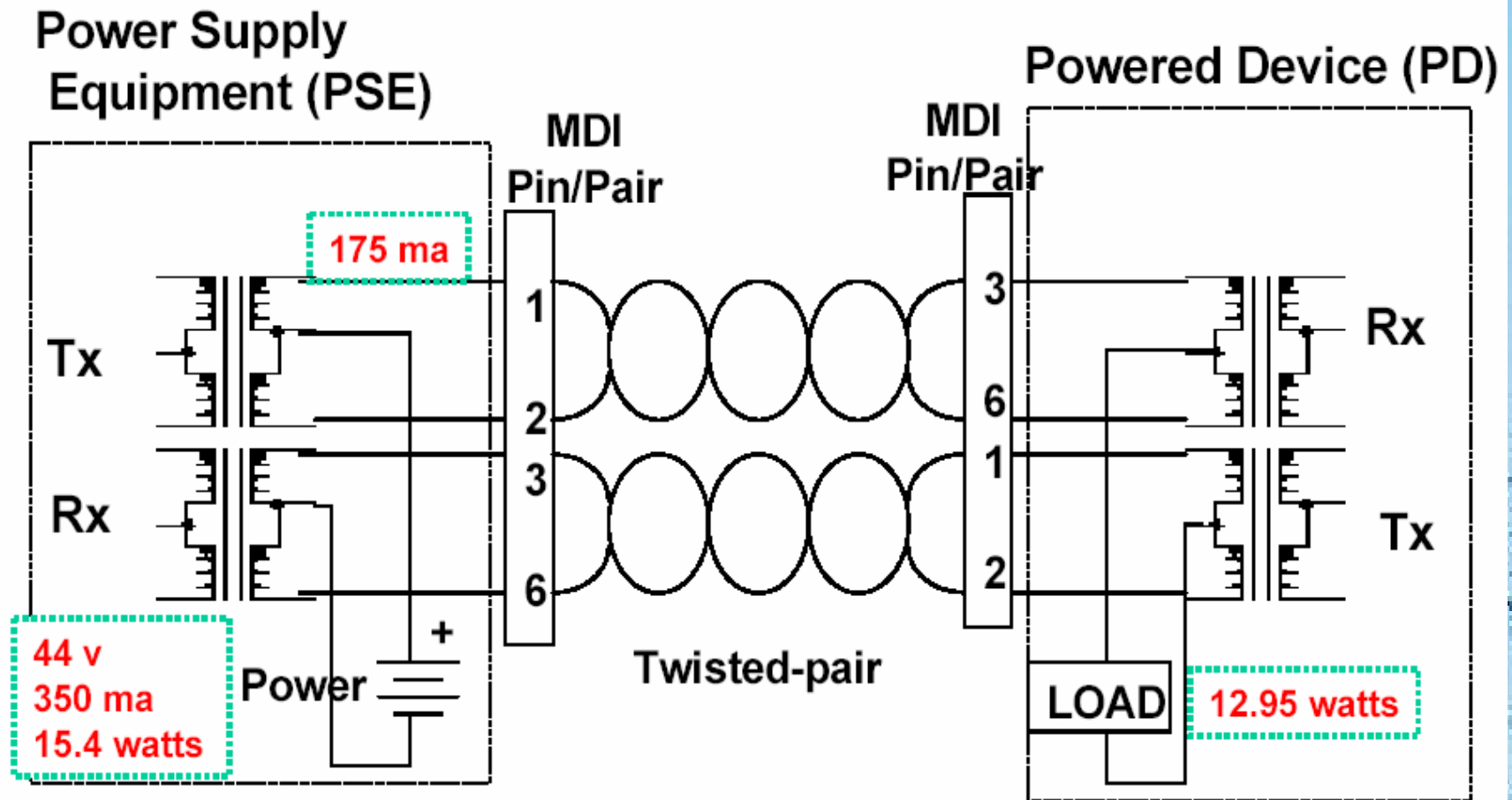
# Power over Ethernet

## Example 2

- 15Vdc feeding
- 12 Vdc powered AP,
- The DC/DC converter can be simple voltage regulator IC
- This will allow for the voltage loss on the cable.
- Similar considerations for a 5 V load



# End Span



- Operating voltage range 37 VDC to 57 VDC
- 12.95 Watts maximum power

**Can support GE, since power and data share the same pairs**



# Powered Device detection signature

- PSE applies test voltages to determine the load characteristic of the PD.
  - The load characteristics of the PD are called the PD detection signature.
  - The PSE reads the PD detection signature to determine whether to supply power and how much power to supply.
  - The detection signature enables the PSE to provide the right level of power, providing a form of power regulation.
- Implemented only in high end switches

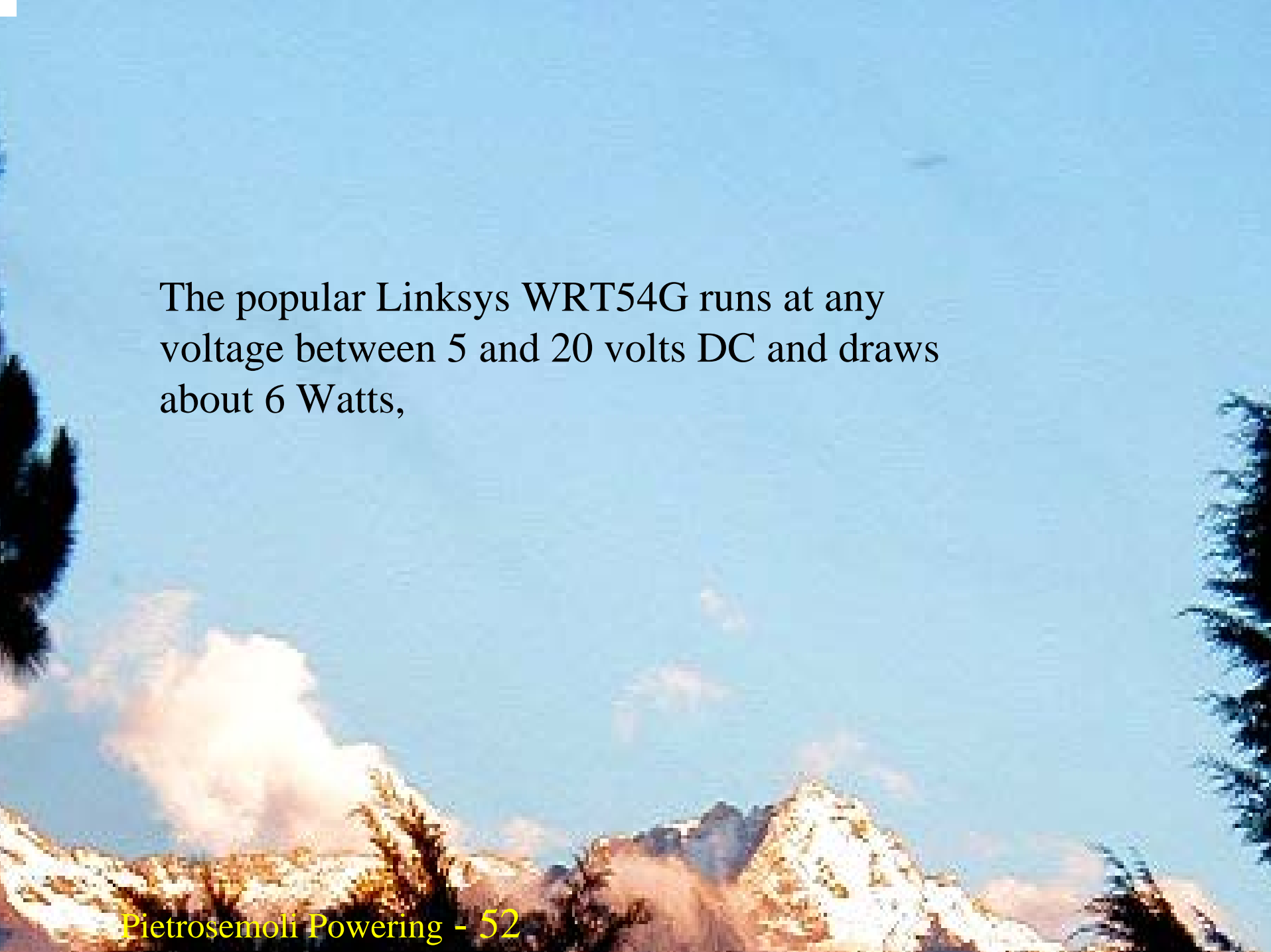
# DIY

- Detailed instructions on how to build your own PoE device can be found at <http://www.nycwireless.net/poe/> and <http://socalfreenet.org/poe>
- A java applet calculator for voltage drop can be found at <http://www.gweep.net/~sfoskett/tech/poecalc.html>  
Beware that this calculator assumes that the voltage drop occurs only in one of the two wires that reach the PD, which is true only if both ends of the cable are attached to the same ground potential

# Remote site powering

Most autonomous solar systems work at 12 or 24 volts. Preferably, a wireless device that runs on DC voltage should be used, operating at the 12 Volts that most lead acid batteries provide. A router or access point that accepts 8-20 Volts DC is perfect. Most cheap access points have a switched mode voltage regulator inside and will work through such a voltage range without modification or becoming hot (even if the device was shipped with a 5 or 12 Volt power supply).

**WARNING:** Operating your access point with a power supply other than the one provided by your manufacturer will certainly void any warranty, and may cause damage to your equipment. While the following technique will typically work as described, remember that should you attempt it, you do so at your own risk.



The popular Linksys WRT54G runs at any voltage between 5 and 20 volts DC and draws about 6 Watts,

# Batteries

Lead acid batteries contain sulfuric acid that can cause severe burns. They release hydrogen when they are charged or have a short between terminals even when they are the sealed acid type. Proper venting is necessary to prevent explosions, especially if the batteries are of the flooded cell acid type. It is a good idea to protect your eyes with safety glasses when handling these batteries.

Lead is toxic - make sure you dispose of worn out batteries properly.

# Calculating and measuring power consumption

The easiest way to measure your device is a laboratory power supply that features a voltage and ampere meter. The nominal voltage provided by a lead acid battery typically varies between 11 Volts (empty) and about 14.5 Volt (charging, voltage at charging limit). You can tune the voltage at the laboratory power supply and see how much current the device draws at different voltages. If a laboratory power supply is not available, measurement can be performed by using the supply shipped with the device. Interrupt one cable that goes to the DC input of your device and insert an *ampere-meter* (or *ammeter*).

# Calculating and measuring power consumption

The amount of power consumed can be calculated with this formula:

$$P = U * I$$

P being Power in Watts, U being voltage in Volts, I being current in Ampere.

For example:

$$6 \text{ Watts} = 12 \text{ Volts} * 0.5 \text{ Ampere}$$

The result is the rating of the device. If the device of the example is operating for an hour it will simply consume 6 Watt-hours (Wh), respectively 0.5 Ampere-hours (Ah).

Thus the device will draw 144 Wh or 12 Ah a day.



# Discharging characteristics - Rule of thumb

A 12 volt lead-acid battery that delivers energy to a consumer provides a voltage depending on its state of charge. When the battery is 100% charged it has an output voltage of 12.8 volts which is quickly dropping to 12.6 volts under load. Beneath 11.6 volt the output voltage is dropping down quickly over time.

Since the battery provides approximately 95% of its power within this linear voltage drop, the charging state could be estimated by measuring the voltage under load. The assumption is that the battery is 100% full at 12.6 V and has 0% charge at 11.6 Volts. So, when measuring a battery that is currently discharged, the status can be estimated with a digital multimeter.



# Discharging characteristics - Rule of thumb

Lead acid batteries degrade quickly when charging cycles go down to 0 charge. A battery from a truck will lose 50% of its design capacity within 50 -150 cycles if it is fully charged and discharged during each cycle.

Never discharge a 12 Volt lead acid battery beneath this value. It will forfeit a huge amount of storage capacity.

In cycle use it is not advisable to discharge a simple truck battery beneath 70%. Not going beneath 80% will significantly increase its durability. Thus a 170 Ah truck battery has only a usable capacity of 34 to 51 Ah.

# Discharging characteristics - Rule of thumb

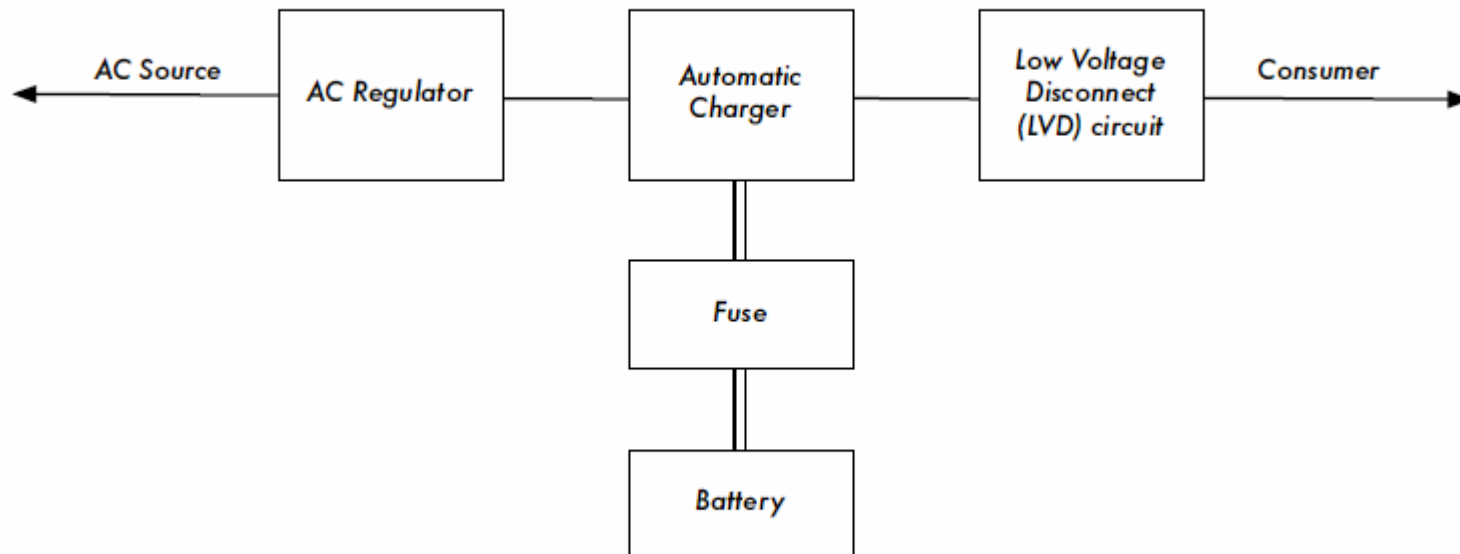
Truck or car batteries that carry the label *maintenance-free* should have neglectable low self-discharge current.

However, maintenance-free batteries still need maintenance.

The level of the electrolyte fluid must be checked frequently, especially in hot climate. If there is loss of electrolyte, distilled water has to be used to fill up the fluid. Neglecting this will ruin the battery.

Charging your batteries too much will destroy them too! The charging current in a battery buffered system must be regulated. Excessive and unlimited charging will destroy the battery.

A battery buffered system looks like this:

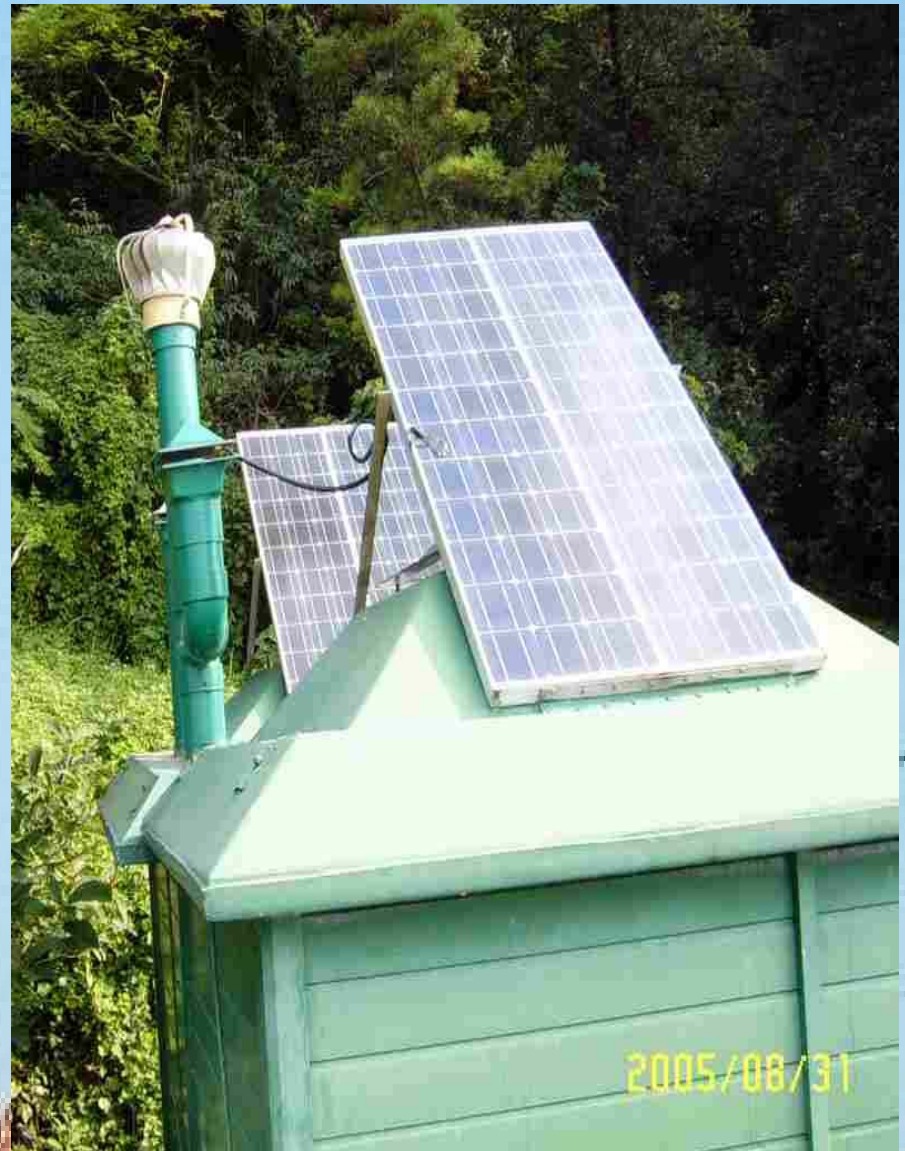


*Figure 7.7: The complete battery buffered system.*

# Designing a solar or wind powered system

Calculating exactly how much energy a solar powered system will produce at a certain site is a lot of work.

Involved in the calculation are factors like temperature, number of sun hours, intensity of radiation, reflections in the environment, alignment of the solar panels and so on..



# Solar power

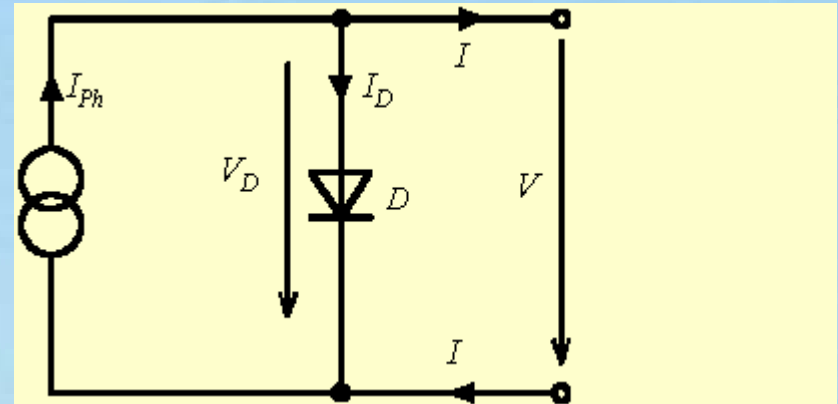
It is important for a solar system that the solar panels are mounted with the best alignment and angle to the sun. The best angle may vary over the year and is dependent on the location of the site. The rule of thumb is towards South in the northern hemisphere and North in the southern hemisphere, with the same inclination as the latitude of the place.

In summer it is better to decrease this value by 10 degrees while in winter it is advisable to increase by the same amount. It is a good idea to take into account that dust, leaves or birds may defile a solar panel. Shade must not wander over the solar panel during the day, because solar panels consist of a number of solar cells that are connected in a daisy chain.



# Solar cell, equivalent circuit and characteristics

The simplified equivalent circuit of a solar cell consists of a diode and a current source which are switched in parallel. The current source generates the photo current  $I_{Ph}$ , which is directly proportional to the solar irradiance  $E$ . The p-n transition area of the solar cell is equivalent to a big diode (in positive polarization)



$$I = I_{Ph} - I_D = I_{Ph} - I_S \cdot \left( \exp\left(\frac{V}{m \cdot V_T}\right) - 1 \right)$$

$I_{Ph}$  Photo current

$I_D$  Diode current

$I_S$  Diode reverse saturation current

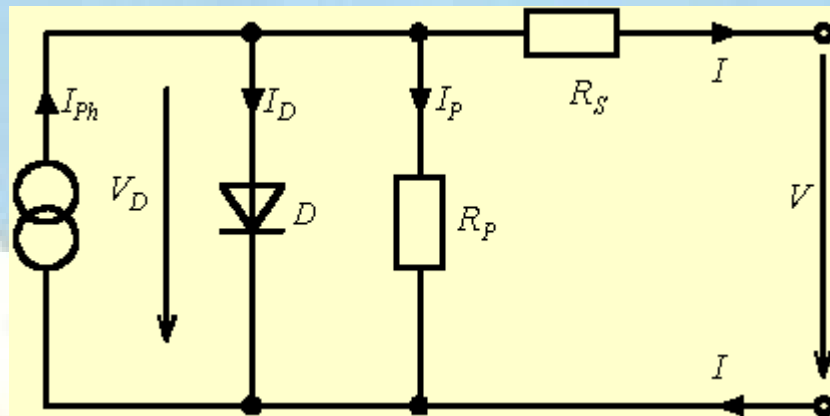
<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

$k$  is Boltzmann constant  $k = 1,380658 \cdot 10^{-23} \text{ JK}^{-1}$

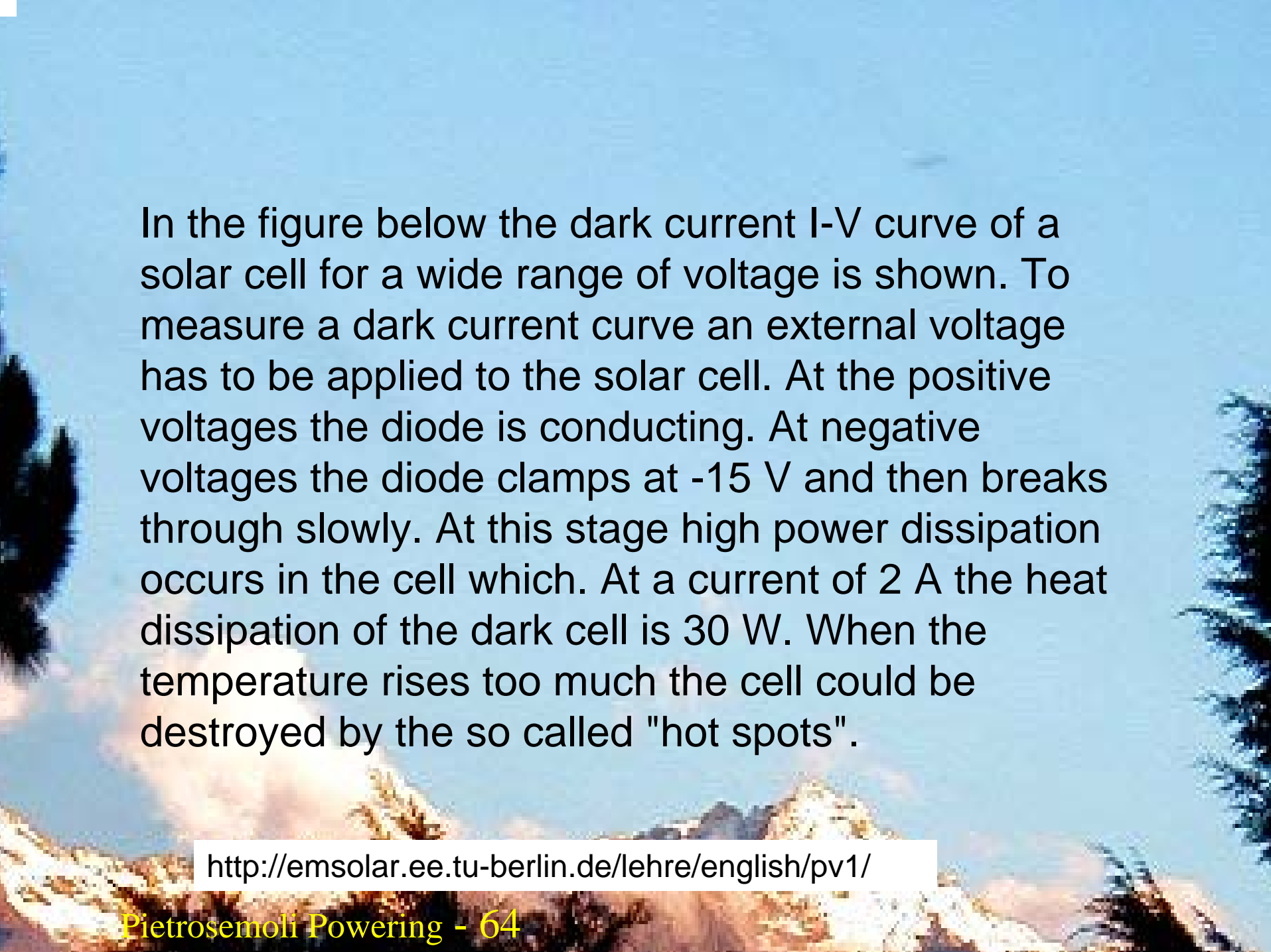
$T$  absolute temperature;  $[T] = \text{K}$  (Kelvin)  $0 \text{ K} = -273,15^\circ\text{C}$

$e$  charge of an electron  $e = 1,60217733 \cdot 10^{-19} \text{ As}$

At real solar cells shows a voltage loss on the external contacts. This voltage loss could be expressed by a series resistor  $R_s$ . Leakage Currents can also be observed, which can be described by a parallel resistor  $R_p$ .



<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

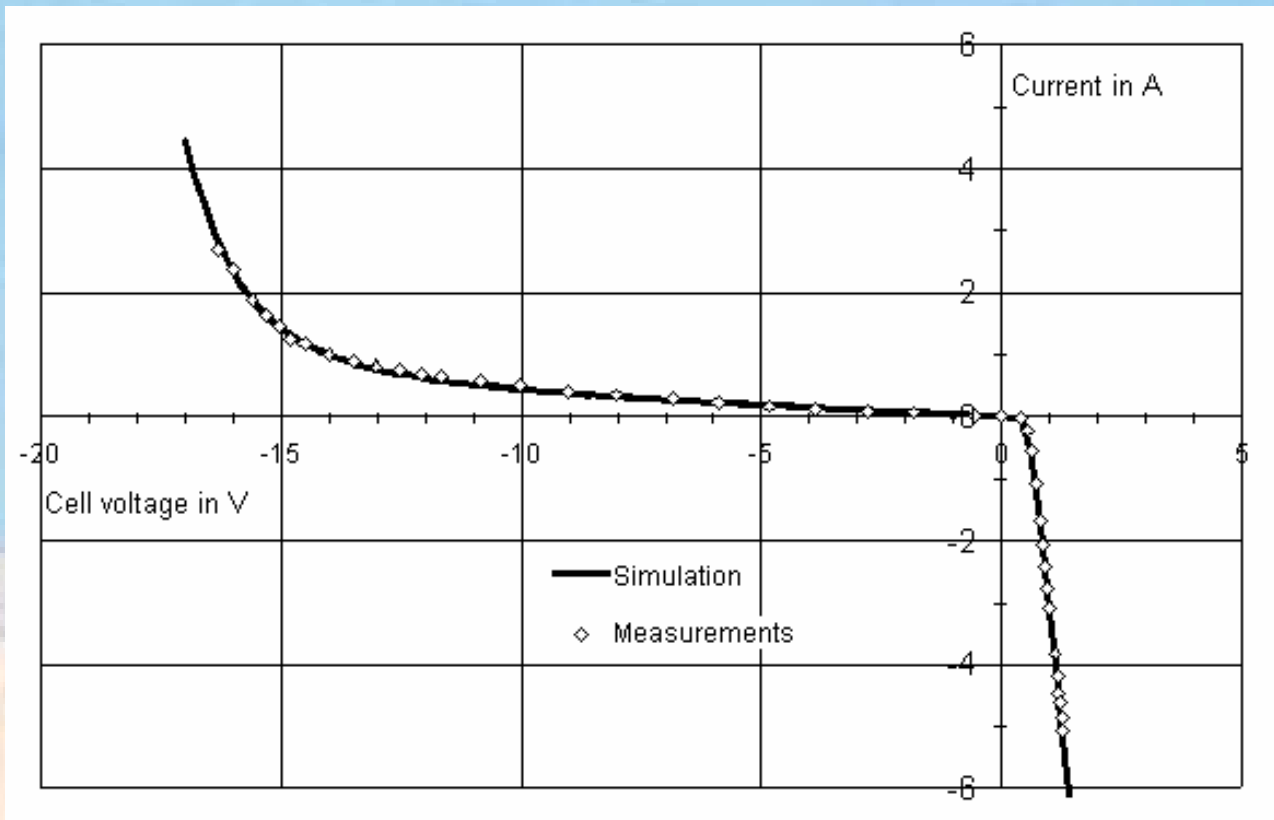


In the figure below the dark current I-V curve of a solar cell for a wide range of voltage is shown. To measure a dark current curve an external voltage has to be applied to the solar cell. At the positive voltages the diode is conducting. At negative voltages the diode clamps at -15 V and then breaks through slowly. At this stage high power dissipation occurs in the cell which. At a current of 2 A the heat dissipation of the dark cell is 30 W. When the temperature rises too much the cell could be destroyed by the so called "hot spots".

<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>



# Dark I-V curve of a solar cell.



<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

If a solar cell is shortcircuited, the current is  $I_{sc}$  and voltage is zero. If no load is applied, the open circuit voltage  $V_{oc}$  could be measured at the terminal. In both cases the electrical output power is 0 W. An irradiated cell is providing power output for a voltage region between 0 V and  $V_{oc}$ . A point of operation where output power is at its maximum is preferred. This specific operation point is called MPP (maximum power point), where voltage times current is maximal. The efficiency of a solar cell could be calculated from the power at MPP  $P_{MPP}$ , the cell area  $A_C$  and the irradiance  $E$  as follows:

$$FF = \frac{P_{MPP}}{V_{oc} \cdot I_{sc}} = \frac{V_{MPP} \cdot I_{MPP}}{V_{oc} \cdot I_{sc}} = \frac{\eta \cdot A_C \cdot E}{V_{oc} \cdot I_{sc}}$$

The fill factor  $FF$ . It is defined as follows:

If the I-V curve would be rectangular (that is the ideal case), the fill factor would be 1. The fill factor is a quality consideration, for real cells it is between 0.75 and 0.85.

<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

# Influence of temperature on the I-V curve

Most of the parameters of a solar cell show a temperature dependency.

The general equation to calculate the temperature coefficient  $TC$  for a value  $y$  is:

$$TC(y) = \frac{1}{y} \cdot \frac{\partial y}{\partial T}$$

If there is a linear connection between the size  $y$  and the temperature  $T$ , the temperature coefficient  $TC$  is:

$$TC(y) = \frac{1}{y(T_0)} \cdot \frac{y(T_1) - y(T_0)}{T_1 - T_0}$$

The short circuit current is increasing at rising temperatures, while losses of the open circuit voltage is about ten times higher (-0.4%/K).

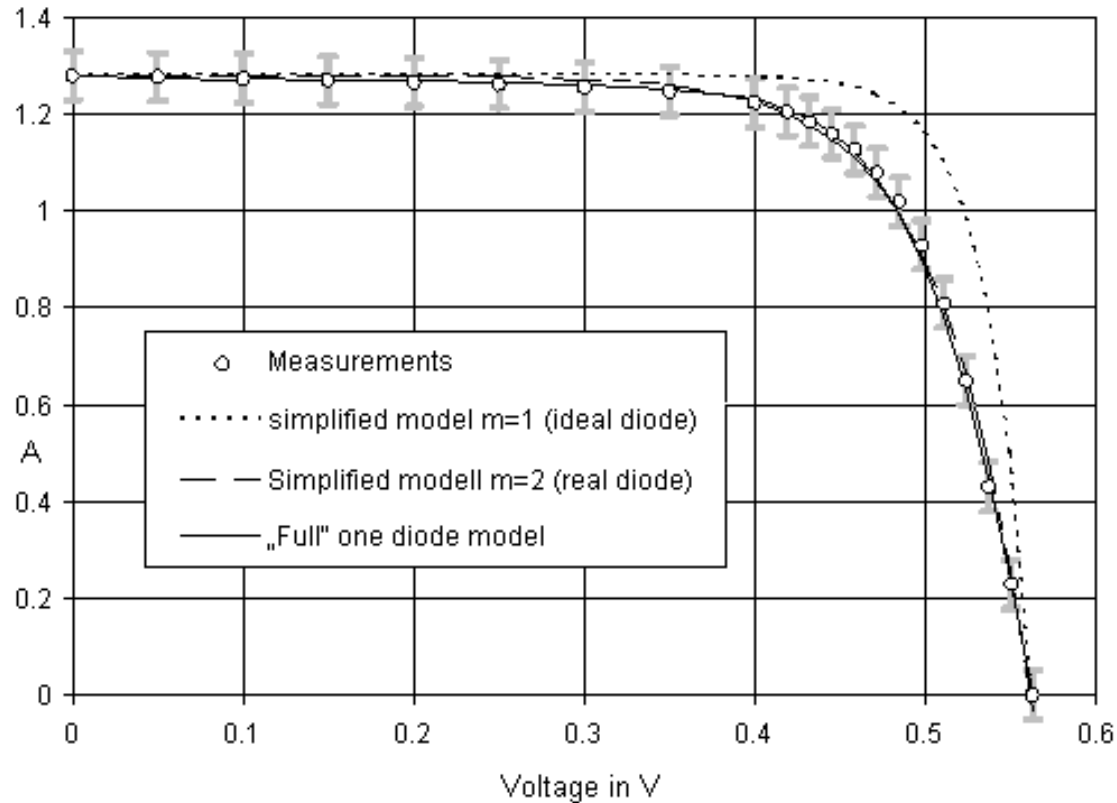
Therefore the power output is decreasing for increasing temperatures.

The power loss factor is around 0.3-0.5 % per degree Celsius, so for an increase of 30°C in temperature the power is decreasing by 9-15 %.

<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

# I-V characteristic of the solar cell

In the figure measurements and calculated I-V characteristics of a multicrystalline solar cell (10 x 10 cm) are compared. irradiance  $E=430 \text{ W/m}^2$ , temperature

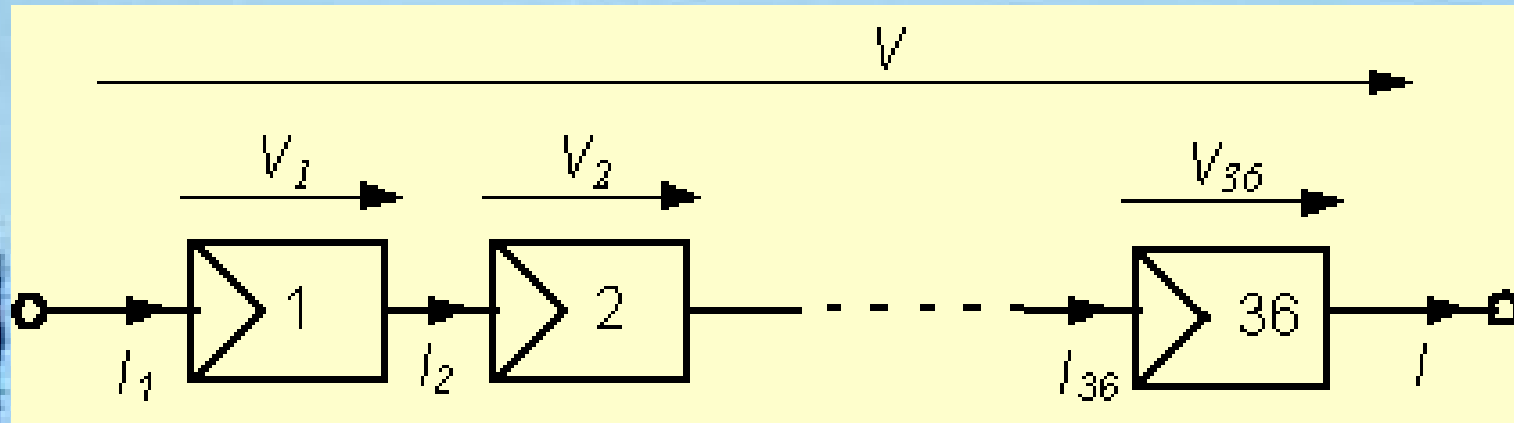


T=300K

<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

# Solar Panel

In a solar panel many cells are connected in series to achieve a higher voltage. Most commercial modules have between 36 and 40 cells

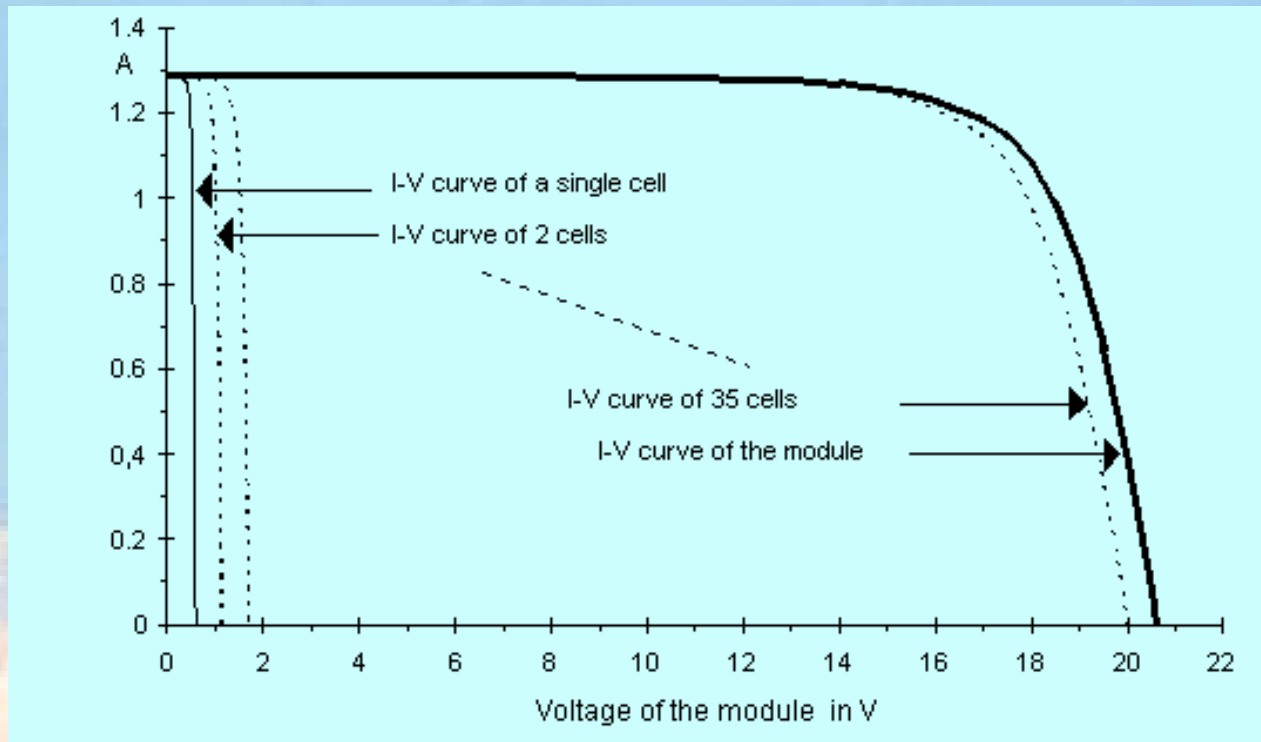


The current through all cells is identical. The voltage of the module consists of the sum of the single voltages  $V_i$  over the  $n$  cells, If the electrical parameters are the same for all cells the Voltage of the module is:  $V = n \cdot V_i$

<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

## I-V characteristics of PV-module (36 cells)

at  $E = 400 \text{ W/m}^2$ ,  $T = 300 \text{ K} = 26^\circ\text{C}$ .

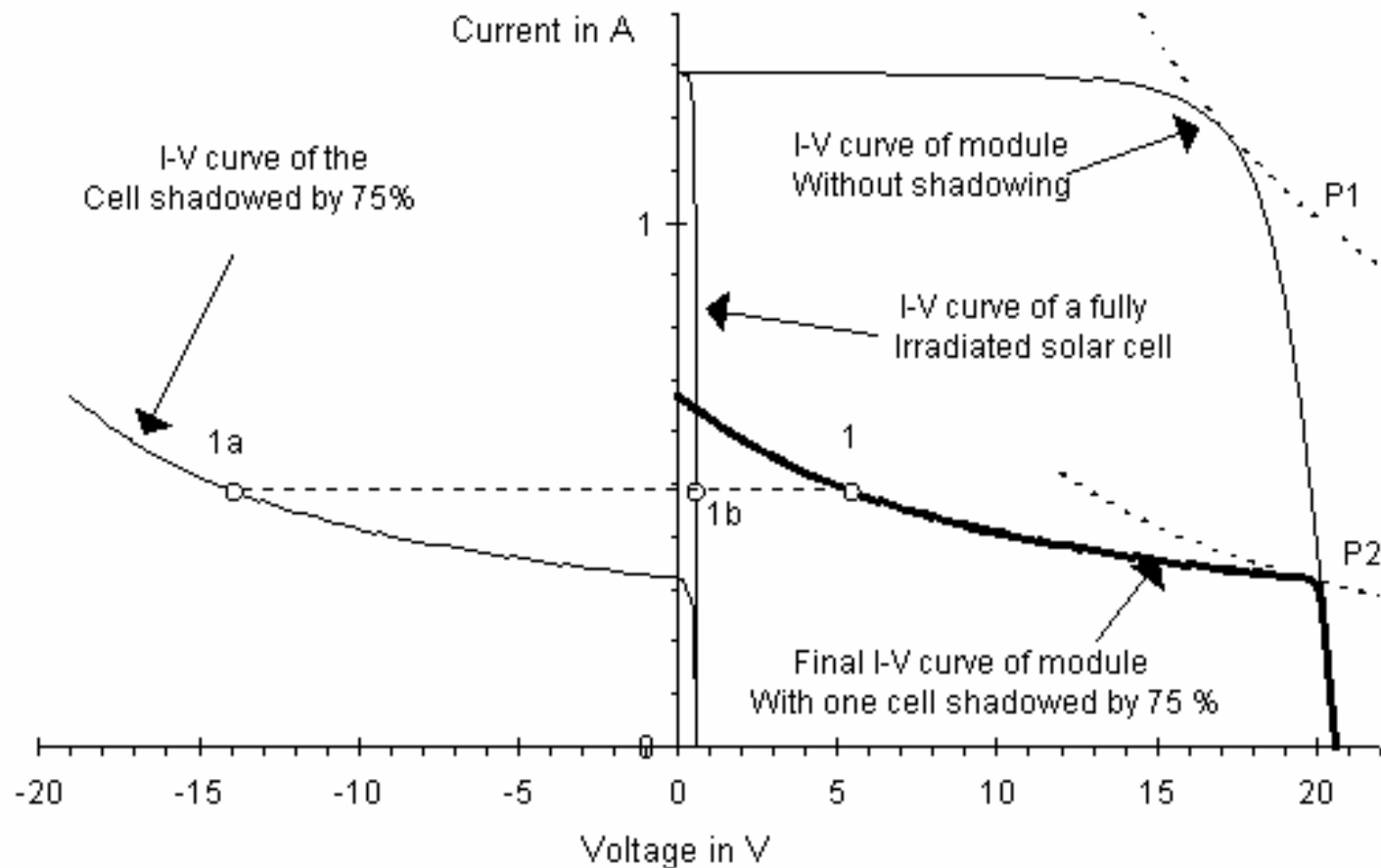


<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

# Influence of shadowing

The I-V curve is affected decisively when cells are irradiated at a different level. In a panel consisting of 36 monocrystalline cells (10 x 10 cm) one cell is shadowed by 75%. All other cells are irradiated completely. The following figure explains the creation of one point at the I-V curve (1): For a given current the voltage is calculated by the addition of the shadowed cell (1a) and 35 times the voltage of a irradiated cell (1b). The final I-V curve is also drawn in the figure: It can be seen that the panel power output is reduced drastically by this single cell shadowing. While the shadowed area is only 2% of the panel area, the power output at MPP is reduced by 70 %. The shadowed cell acts as a load. The maximum power dissipation at this cell is 12.7 W occurring at short circuit of the module. The points of the maximum power  $P1$  and  $P2$  are marked in the curves of identical power output.

<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

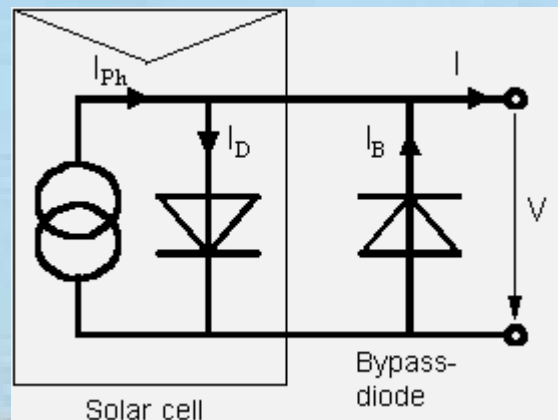


<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>



# Bypass-diodes

In the shadowed cell there is the threat of overheating. Therefore the manufactures of PV-modules install bypass diodes to the strings of cells. If the cells are operated at negative voltages, the current passes through the bypass diode. The voltage at the cells is limited to the threshold of the passing operation of the diode.



<http://emsolar.ee.tu-berlin.de/lehre/english/pv1/>

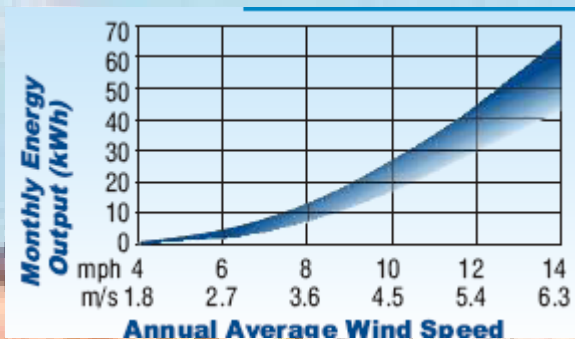
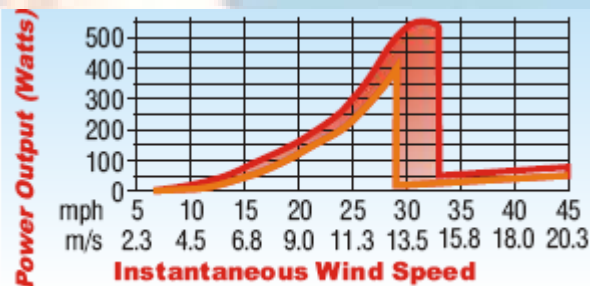
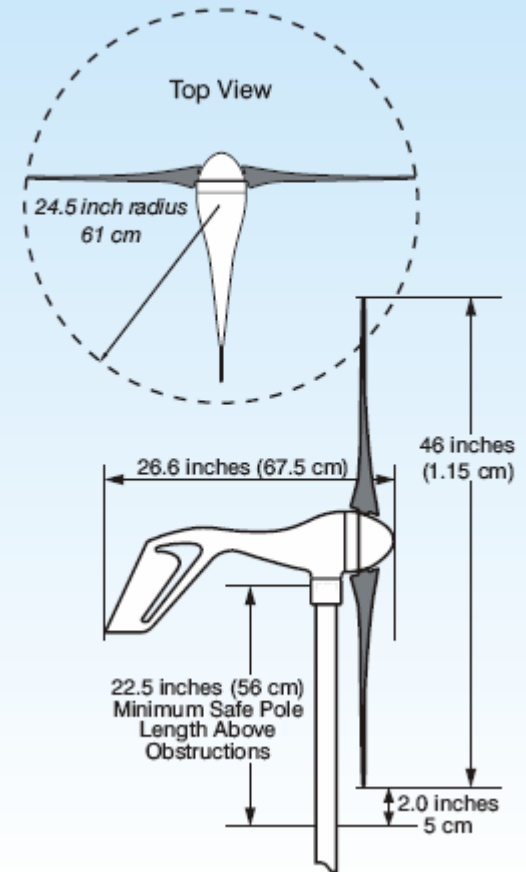
# Wind power

A wind generator is a clear option when an autonomous system is being designed for a wireless relay to be built on a hill or mountain. A concern for wind power is that the wind speed must be high enough at a site which may be surrounded by objects. The average wind speed over the year should be at least 3 - 4 meter per second, and the wind generator should be 6 meters higher than other objects within a distance of 100 meters. A location far away from the coast usually lacks sufficient wind energy to support a wind powered system.

# Wind Power



## Sphere of Operation



# Specifications

Rotor Diameter:	46 inches (1.15m)
Weight:	13 lbs (5.85kg)
Shipping Dimensions:	Shipping: 27"x15"x9" (686x38x228mm) / 17 lbs (7.7kg))
Mount:	1.5" schedule 40 pipe (1.9" OD, 48 mm)
Start-up wind speed:	8 mph (3.58 m/s)
Voltage:	12, 24, 34 and 48 VDC
Rated Power:	400 watts at 28mph (12.5m/s)
Turbine Controller:	Microprocessor-based smart internal regulator with Peak Power Tracking
Body:	Cast aluminum (Air-X Marine is powder coated for corrosion protection)
Blades (three):	Carbon Fiber Composite
Over-speed Protection:	Electronic torque control
Kilowatt hours per month:	38 kWh/mo @12mph (5.4m/s)
Warranty:	3 Year Limited Warranty
Survival Wind speed :	110 mph (49.2 m/s)

## *The AIR-X Features:*

**Electronics:** The microprocessor based controller provides voltage regulation, peak power tracking, and quiet, stall control in high winds. It uses a synchronous rectifier bridge which results in cooler, more efficient operation.

**Alternator:** designed to complement the peak power tracking ability of the control electronics. The strong permanent magnet rotor can be felt in rotating the rotor shaft; a slight “catch” can be felt when spinning the shaft with your fingers. This is normal, and is quickly overcome when the blades begin spinning.

**Blades:** Manufactured using a precision injection molding process that produces blades of exceptional consistency. The AIR-X blades have an increased tip angle which improves their ability to start rotating, and moves “flutter” to higher wind speeds. The control electronics will slow the blades before the turbine reaches the point of flutter.

## ***The AIR-X Features:***

**New Yaw Shaft:** The yaw shaft is the part of the turbine that mounts to the tower and allows the turbine to rotate into the wind.

**Hysteresis Braking:** The regulation control circuitry incorporates hysteresis. This will lock the turbine in a silent regulation mode once the batteries are fully charged. The turbine begins producing power again when the battery voltage drops slightly below fully charged. This means, for a factory set 12V turbine, the turbine will regulate (shut down) when the batteries have reached 14.1V, and will resume charging when the voltage drops to 12.75V.

**New Body, New Hub:** The *AIR-X* body is made from a precision casting process that not only enhances fit and finish, but also leads to a stiffer, more durable body. The aluminum casting also acts as a heat sink and transfers heat from the stator and the electronics into the wind flowing past the turbine. The die cast aluminum hub design has been engineered to be the strongest, stiffest hub we have ever produced.



# ***SAFETY PRECAUTIONS***

**Safety must be the primary concern as you plan the location, installation and operation of the turbine. At all times be aware of electrical, mechanical and rotor blade hazards.**

## ***1.1 Mechanical Hazard***

Rotating blades present the most serious mechanical hazard. The ***AIR X***'s rotor blades are made of very strong thermoplastic. At the tip, the blades may be moving at velocities over 275 miles per hour (440 km/hr). At this speed, the tip of a blade is nearly invisible and can cause serious injury.

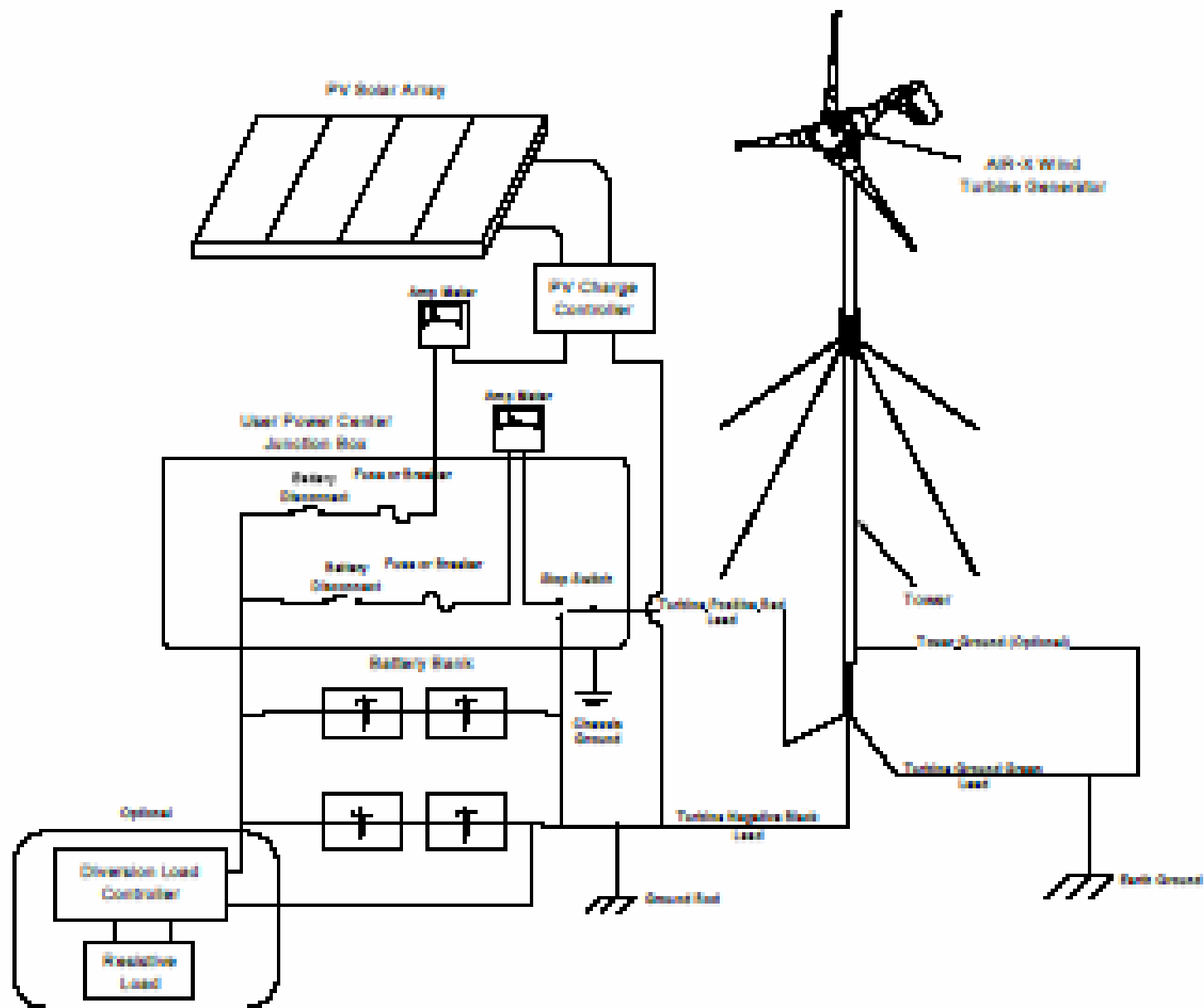
***Under no circumstances should you install the turbine where a person could come in contact with moving rotor blades.***

## ***1.2 Electrical Hazards***

The internal electronics of the ***AIR-X*** prevent open circuit voltages from rising above 20 volts for 12-volt systems or above 40 volts for 24-volt systems.

Please note that the inherent personal dangers from electrical current still exist, therefore caution should always be used when connecting this and other electrical devices.

### C. AIR-X In a System With Solar Panels (Hybrid System)





## ***SITING***

In any location, the closer you get to the surface of the earth, the slower the wind speed. This is a result of the friction of the earth and obstacles on the surface. Turbulence caused by obstacles will reduce the efficiency of any wind turbine.

Therefore, locate the turbine in a site that has the “cleanest” free-flowing wind possible.

Power in the wind is the cubic function of the wind speed. This means that small changes in wind speed can have dramatic changes in output. Each time the wind speed doubles, the power increases eight times!

The ***AIR-X*** should be mounted on a tower a minimum of 25' (8 meters) above any surrounding objects within a 500' (150 m) radius. If this is not possible, then place it as high as you can. If this is a roof top installation, it is important there are no objects around the structure that may block the wind.